

GE Vernova

Reason RT430/RT434

GNSS Precision-Time Clock



Technical Manual

Platform Hardware Version: B

Platform Software Version: 08

Publication Reference: RT430-RT434-GNSS-TM-EN-HWB-8v13



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Table of Contents

Table of Contents	3
Table of Figures	8
List of Tables	10
Chapter 1: Introduction	12
1 Foreword	12
1.1 Target Audience	12
1.2 Acronyms and abbreviations	13
2 Product Scope	14
3 Available Models	15
4 Key Features	15
4.1 GNSS	17
4.2 PTP / SNTP / NTP	17
4.3 Parallel Redundancy Protocol (PRP)	17
4.4 Stationary Mode	17
4.5 Time Sync Flexibility	18
4.6 Environmental Robustness	18
5 Functional Overview	19
6 Standards Compliance	19
Chapter 2: Safety Information	20
1 Health and Safety	20
2 Symbols	21
3 Installation, Commissioning and Servicing	21
3.1 Lifting Hazards	21
3.2 Electrical Hazards	22
3.3 Fusing Requirements	23
3.4 Equipment Connections	23
3.5 Pre-energization Checklist	25
3.6 Peripheral Circuitry	25
3.7 Upgrading/Servicing	26
4 Decommissioning and Disposal	26
Chapter 3: Hardware Design	27
1 Front View	27
2 Rear View	27
3 Network Ports	28
4 Power Supply	28

Chapter 4: Installation	30
1 Unpacking	30
1.1 Normal Use of the Equipment	30
1.2 External Indications	30
2 Mounting	31
2.1 Power Supply	31
2.2 Grounding (Earthing)	32
2.3 GNSS Antenna Terminal	33
2.4 TTL Electrical Outputs	35
2.5 Open-Collector Electrical Outputs	35
2.6 Optical Outputs	37
2.7 Amplitude Modulated Output	37
2.8 Serial Port (RS232, RS422/485)	37
2.9 Dry-Contact Relay	38
2.10 Event Input	39
2.11 Euro Type Connections	39
3 Ethernet Communication	40
3.1 Factory default settings	40
3.2 Network port and communication protocols	41
3.3 Equipment access	42
4 Powering Up	42
5 Preventive Maintenance Actions	42
5.1 Preventive Actions	43
Chapter 5: Operation	44
1 Local Interface (HMI)	44
2 Web Interface (Remote Access)	45
2.1 Web Interface Language	46
3 Monitoring Menus – Web Interface	46
3.1 Status	46
3.2 General Information	48
3.3 Event Log	48
Chapter 6: Configuration	50
1 Web Interface	50
1.1 User Name and Password	50
1.2 Sending Configuration	51
2 Ethernet	51
2.1 PRP (only in RT430)	51
2.2 Ethernet Ports	52
2.3 Default Gateway	52
2.4 DNS Server	52

2.5	Ethernet - Configuration Summary	53
3	Time Settings	53
3.1	Time Parameters	54
3.2	Network Time Protocol (NTP)	54
3.3	Time Settings - Configuration Summary	55
4	Time Signals	55
4.1	Outputs	56
4.2	Serial datagram	57
4.3	Customizable datagrams	58
4.4	Time Signals - Configuration Summary	59
5	PTP Configuration	61
5.1	Comparison between PTP Power Profiles	62
5.2	PTP Profiles	63
5.3	Domain number	65
5.4	Network protocol	66
5.5	Operation mode	66
5.6	Delay mechanism	66
5.7	Grandmaster Priority	66
5.8	PTP Messages	66
5.9	PTP - Configuration Summary	67
6	Setup	68
6.1	Configuration Management	70
6.2	Password configuration	70
6.3	Reset Satellites Almanac	70
6.4	Stationary Mode	70
6.5	Demo mode	71
6.6	Log Files	71
6.7	Reboot System	71
6.8	Generate HTTPS Certificate	71
7	Cyber Security Notice	72
Chapter 7: Maintenance		73
1	Time Synchronization Failure (Locked Signaling)	73
1.1	Locked indicator (HMI)	73
1.2	Remote monitoring (Web Interface)	74
1.3	Dry-contact relay (Locked)	74
1.4	IRIG-B Signal	74
1.5	PTP Protocol	74
1.6	NTP Protocol	74
1.7	SNTP Protocol	75
2	Firmware Update	75
3	Equipment Upgrade - Key Change	75
4	Cleaning Instructions	76

5	Equipment Return	76
Chapter 8: Technical Specification		77
1	Power Supply	77
2	GNSS Antenna	77
2.1	GNSS Antenna Receiver	77
2.2	GNSS Antenna Type	78
2.3	Antenna Cable	78
2.4	Surge Arrester	79
3	Internal Oscillator	79
4	Outputs	80
4.1	Connectors	80
4.2	TTL Electrical Outputs	81
4.3	Open Collector Electrical Outputs	82
4.4	Optical Outputs	82
4.5	Amplitude Modulated Output	82
4.6	Serial Port (RS232, RS422/485)	83
5	Dry-contact Relay	83
6	Event Input	84
7	Precision Time Protocol PTP (IEEE 1588)	84
8	Ethernet Ports	84
9	Environment	85
10	Type Tests	86
11	Dimensions, Weight	88
Chapter 9: Ordering Options		90
1	RT430 GNSS Cortec	91
2	RT434 GNSS Cortec	92
Chapter 10: Appendixes		93
Appendix A – IRIG-B Standard Summary		93
Appendix B – PTP Standard Concepts (IEEE1588)		98
11.1	Description	98
11.2	Definitions according to IEEE 1588 Standard	98
11.3	Multicast and Unicast Networks	99
11.4	PTP Synchronization	100
11.5	Network protocols	101
11.6	Clock operation mode	101
11.7	Delay measurement mechanism	101
11.8	Master, Slave and Grandmaster clocks	102
11.9	PTP Messages	102
Appendix C – Serial Datagrams		104

11.10 ACEB Datagrams	104
11.11 NEMEA GPZDA Datagram	104
11.12 Meinberg Datagram	106
Appendix D – Antenna Delay Compensation	107
11.13 Signal Attenuation	107
11.14 Propagation Delay	107
Appendix E – Application Examples	109
11.15 Application Example 1: Traditional and Modern Time Sync	109
11.16 Application Example 2: System Wide Grandmaster Clock	109
11.17 Application Example 3: Synchrophasor, TWFL and Process Bus Applications	110
11.18 Application Example 4: IEEE 1588 in a PRP Network	111
11.19 Application Example 5: Time Sync Expansion using RT411 and RT412	112
Appendix F – Kit Mounting for GNSS Antenna (Q065)	113

Table of Figures

Figure 1: Functional Overview of RT430/434	19
Figure 2: Front view of RT430	27
Figure 3: Front view of RT434	27
Figure 4: Rear view of RT430	28
Figure 5: Rear view of RT434	28
Figure 6: Location of Serial number, part number and outputs description.	31
Figure 7: Pre-insulated tubular pin terminals	31
Figure 8: Supply connector assembly	32
Figure 9: RT430/RT434 Power Connection	32
Figure 10: RT430/434 Grounding Strap	33
Figure 11: GNSS antenna connector	33
Figure 12: Recommended position for installing the GNSS Antenna	34
Figure 13: Recommended position GNSS Antenna conduit installation	34
Figure 14: TTL electrical outputs	35
Figure 15: Open collector electrical outputs	36
Figure 16: Connection diagram of the open-collector electrical outputs	36
Figure 17: Optical outputs	37
Figure 18: Amplitude modulated output	37
Figure 19: Serial port RS232 and RS422/485	37
Figure 20: Dry-contact relay	38
Figure 21: Event input	39
Figure 22: Euro Type label for connections	39
Figure 23: Electrical communication interface via Ethernet network	40
Figure 24: Local Interface from RT430 and RT434	44
Figure 25: Navigating the RT430's local monitoring display	44
Figure 26: RT430 Web Interface	46
Figure 27: Languages available in the Web Interface	46
Figure 28: Section to monitor the status of the unit in the Web Interface	47
Figure 29: Section to visualize general information of the system	48
Figure 30: Section of Web Interface to monitor timestamps of event input	48
Figure 31: Section to configure network parameters of the unit	51
Figure 32: Enabling the PRP redundancy	52
Figure 33: Section to configure time parameters	53

Figure 34: Section to configure time signals applied in the outputs	56
Figure 35: Section to configure PTP parameters	61
Figure 36: Characteristics from Power Profile, in accordance with IEEE C37.238:2017	64
Figure 37: Characteristics from PTP for Power Utility Automation, in accordance with IEC/IEEE 61850-9-3:2016	64
Figure 38: Characteristics from PTP Power Profile IEEE C37.238:2011	65
Figure 39: Setup section in Web Interface	69
Figure 40: Manual Time setting – only available in Demo Mode	71
Figure 41: Section to update firmware	75
Figure 42: Section to equipment upgrade – key change	76
Figure 43: Rear panel connectors of RT430 (top) and RT434 (bottom)	80
Figure 44: RT430/434 Dimensions	89
Figure 45: Traditional x Modern Time Synchronization	109
Figure 46: System Wide Grandmaster Clock	110
Figure 47: Synchrophasor devices synced by RT430/434	110
Figure 48: TWFL application using RT430/434 for Time Sync	111
Figure 49: Process Bus application using PTP via the Station Bus network.	111
Figure 50: PTP in a PRP network.	112
Figure 51: Time Sync expansion using RT411 and RT412	112
Figure 52: Dimensions of antenna kit mounting	113
Figure 53: Items from antenna kit mounting	114

List of Tables

Table 1: Serial port pinout	38
Table 2: Ethernet port 1 default settings	40
Table 3: Ethernet port 2 default settings	40
Table 4: Ethernet port 3 default settings (RT434)	40
Table 5: Ethernet port 4 default settings (RT434)	41
Table 6: Gateway and DNS Server default settings	41
Table 7: Network port and communication protocols	41
Table 8: Factory default username and password	50
Table 9: Summary of configurable network parameters	53
Table 10: Summary of configurable time parameters	55
Table 11: Customizable datagram special characters	58
Table 12: Summary of all configurable parameters for outputs	60
Table 13: Comparison between PTP Power Profiles	63
Table 14: Summary of configurable PTP parameters	67
Table 15: Power supply specifications	77
Table 16: GNSS Antenna input specifications for temporal synchronization	77
Table 17: GNSS Antenna specifications	78
Table 18: Antenna Cable specifications	78
Table 19: Surge arrester specifications	79
Table 20: Internal oscillator specifications	79
Table 21: RT430/434 rear panel connectors	80
Table 22: Electrical outputs specifications	81
Table 23: Open collector outputs specifications	82
Table 24: Optical outputs specifications	82
Table 25: Amplitude modulated output	82
Table 26: RS232 or RS422/485 serial port specifications	83
Table 27: Dry-contact relay specification	83
Table 28: Event Input specification	84
Table 29: PTP time synchronization protocol specifications	84
Table 30: Ethernet ports specification	85
Table 31: Environment specification	85
Table 32: Enclosure Protection IEC 60529	85

Table 33: EMC tests were performed according to IEC 60255-26 referring to the following standards	86
Table 34: Safety tests	87
Table 35: Environmental tests	88
Table 36: Dimensions and weight specification RT430/434	88
Table 37: IRIG-B standard summary	93
Table 38: ACEB Datagram Information	104
Table 39: GPZDA Datagram Time Information	105
Table 40: GPZDA Datagram Line Feed and Carriage Return Information	105
Table 41: GPZDA Datagram Checksum Information	105
Table 42: Meinberg Datagram Time Information	106
Table 43: Meinberg Datagram Beginning and End Information	106
Table 44: Meinberg Datagram Locked State Information	106
Table 45: Antenna cables attenuation @ 1500 MHz (± 1 dB)	107
Table 46: Attenuation of typical antenna cables	108
Table 47: Dimensions specification of antenna kit mounting	113
Table 48: Description of items from kit mounting	113

Reason RT430/RT434

GNSS Precision-Time Clock

Chapter 1: Introduction

This chapter provides general information about the technical manual and an introduction to RT430 and RT434 GNSS Precision-Time Clocks.

1 Foreword

This technical manual provides a functional and technical description of GE Reason RT43X Precision-Time Clocks, as well as a comprehensive set of instructions for using the devices. The level at which this manual is written assumes that you are already familiar with protection engineering and have experience in this discipline. The description of principles and theory is limited to that which is necessary to understand the product.

We have attempted to make this manual as accurate, comprehensive and user-friendly as possible. However, we cannot guarantee that it is free from errors. Nor can we state that it cannot be improved. We would therefore be very pleased to hear from you if you discover any errors, or have any suggestions for improvement. Our policy is to provide the information necessary to help you safely specify, engineer, install, commission, maintain, and eventually dispose of this product. We consider that this manual provides the necessary information, but if you consider that more details are needed, please contact us.

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1.1 Target Audience

This manual is aimed towards all professionals charged with installing, commissioning, maintaining, troubleshooting, or operating the Reason RT43X product line. This includes installation and commissioning personnel as well as engineers who will be responsible for operating the product. The level at which this manual is written assumes that installation and commissioning engineers have knowledge of handling electronic equipment. Also, system and protection engineers have a thorough knowledge of protection systems and associated equipment.

1.2 Acronyms and abbreviations

AC - Alternating Current;
ASCII - American Standard Code for Information Interchange;
BMC - Best Master Clock;
BNC - Bayonet Neil Councilman connector;
bps - Bits per second;
CAT5 - Network Cable;
CMOS - Complementary Metal-Oxide-Semiconductor;
DB9 - Connector do type D-subminiature;
DC - Direct Current;
DCF77 - Time synchronization protocol Deutschland LORAN-C (Long Range Navigation - C) Frankfurt 77 (77.5 kHz);
DMARK – Single pulse with a programmable date and time;
DNS - Domain Name System;
DST - Daylight Saving Time;
DTE - Data Terminal Equipment;
E2E - End-to-end;
ETH - Abbreviation of the term Ethernet;
FW - Abbreviation of the term Firmware;
GLONASS - GLObal NAVigation Satellite System from Russian Aerospace Defense Forces;
GND - Abbreviation of the term Ground;
GNSS - Global Navigation Satellite System;
GPS - Global Positioning System;
GPZDA - Serial Datagram format;
HTTP - Hypertext Transfer Protocol;
HTTPS - Hypertext Transfer Protocol Secure;
IEC - International Electrotechnical Commission;
IED - Intelligent Electronic Devices;
IEEE - Institute of Electric and Electronic Engineers;
HMI - Human-Machine Interface;
IP - Internet Protocol;
IP40 - Degree of protection 40;
IRIG-B - Time synchronization protocol Inter Range Instrumentation Group (Rate Designation B);
LCD - Liquid Crystal Display;
MAC - Media Access Control;
MIB - Management Information Base;
NTP - Network Time Protocol;
OUT - Abbreviation of the term Output;
P2P - Peer-to-peer;
PPM - Pulse per minute;
PRP - Parallel Redundancy Protocol;
PPS - Pulse per Second;
PPX - Pulse per X s;
PTP - Precision Time Protocol;
RAIM - Receiver Autonomous Integrity Monitoring;
RJ45 - Ethernet Connector with 8 conductors;
RS232/485 - Serial port levels;
RX - Receiving data;

SNMP - Simple Network Management Protocol;
SNTP - Simple Network Time Protocol;
ST - Bayonet-lock connector;
TCP - Transmission Control Protocol;
TMARK - Daily pulses with programmable time;
TTL - Transistor-to-Transistor logic;
TX - Data transmission;
UDP - User Datagram Protocol;
UTC - Universal Time Coordinate.

2 Product Scope

RT430/434 is a GNSS clock referenced to GPS and GLONASS satellites, whose main application is to be a source of temporal synchronization signals in different formats and protocols to synchronize internal clocks of equipment and systems based on digital processing.

The RT430/434 is ruggedized and specifically designed for operation and to be part of the large scale electrical fixed installations, as electrical power generation installations, electrical substations and electrical utilities control systems.

With nanosecond time accuracy, the RT430/434 provides temporal synchronization for applications as synchrophasor measurement, traveling wave fault location, current differential protection operating over SONET and MPLS systems, and others.

The time synchronization protocols supported are:

- PTP (Precision Time Protocol) according to IEEE 1588v2:2008;
- Operates as a PTP master clock or ordinary clock;
- PTP Power Profile, in accordance with latest IEEE C37.238:2017 and its previous 2011 version;
- PTP Profile for Power Utility Automation, in accordance with IEC 61850-9-3:2016 standard;
- NTP/SNTP;
- IRIG-B004 (Demodulated);
- IRIG-B124 (Modulated);
- DCF77;
- Serial Datagram;
- Low frequency pulses, as PPS, PPM and others configurable options.

RT430/434 GNSS features a TCXO as standard internal oscillator for accurate free-running time reference when not synchronized by satellite. Furthermore, it is free from any internal battery, using a supercapacitor instead., negating environmental concerns and avoiding the need for periodic battery replacement.

The RT430 is the first clock to offer Parallel Redundancy Protocol (PRP). Profit from the high-availability, reliability, and security of your Ethernet network to distribute time accurately and economically over the same network used on your digital substation.

The front display of the RT430/434 shows either local or UTC date and time, considering the DST rules when defined by the user.

3 Available Models

RT430 is available in different versions, depending on the features required in each of the two Ethernet network interfaces, including PRP for both, and the quantity and input voltage range of the power supplies.

Apart from the PRP, the RT434 has the same functions and protocols as RT430. The RT434 versions depends on the features required by each of the two pairs of Ethernet network interfaces, and the quantity and input voltage range of the power supplies.

The Cortecs from RT430 and RT434 demonstrate the available versions for ordering.

4 Key Features

- GNSS clocks - GPS and GLONASS satellite systems as reference;
- Mean time accuracy of 50 ns for IRIG-B/PPS signals;
- IEEE 1588v2 PTP protocol, with better than 100ns accuracy;
- PTP Power Profile, in accordance with latest IEEE C37.238:2017 and its previous 2011 version;
- PTP Profile for Power Utility Automation, in accordance with IEC 61850-9-3:2016 standard;
- NTP/SNTP time server;
- PTP and NTP/SNTP simultaneously through each Ethernet port;
- High accuracy free-running TCXO internal oscillator, ensuring holdover stability;
- Parallel Redundancy Protocol (PRP) in accordance with IEC 62439-3:2016 (only in RT430);
- Status monitoring using SNMP (v1, v2c) including MIB support;
- Stationary Mode to keep a locked synchronization even with only one satellite;
- Event input to analyze time quality from external events;
- Delay compensation for GNSS antenna cables;
- Time signals in IRIG-B004, IRIG-B124, or DCF77 format;
- Pulses: 100 pulses-per-second, 1 pulse-per-second, 1 pulse-per-minute;
- Freely configurable low frequency pulse generator;
- Pulse on-time with daily repetition;
- User-configurable rules for daylight-saving-time and configurable time zone;
- Web Interface for configuring and monitoring, available in five different languages: English, French, Spanish, Portuguese and Russian
- RS232 and RS422/485 serial ports with frequency variable pulse and datagram;

- Independent Ethernet network ports 10/100Base-T for configuration and access to the equipment;
- Indicators for monitoring synchronization of GNSS antenna and equipment status;
- 19" Panel Installation;
- Full range power supplies;
- Redundant power supply.

4.1 GNSS

The demand for accurate time synchronization available 24/7 increases with the growth of critical substation applications, such as phasor measurement, merging units, traveling-wave fault location and current differential protection operating over SONET and MPLS systems. RT430/434 GNSS now tracks GPS and GLONASS satellites concurrently, and whenever one constellation is lost, or reports bad quality, the clock will continue running in full synchronization based on the healthy source (with zero switchover time). Using GNSS is also a great way to guarantee time availability when the antenna is installed in places close to buildings or mountains, as the clock has more satellites as time reference, offering greater immunity to “shadow” effects.

4.2 PTP / SNTP / NTP

The Reason RT430/434 offers the accurate PTP time protocol, which is defined by the IEEE 1588 standard, to precisely synchronize IED's and computers over a LAN (or VLAN). Besides, using PTP is a great solution to synchronize multiple clocks with a better than 100ns time accuracy over Ethernet networks.

As designed by the IEEE 1588, RT430/434 may operate either as the “PTP Grandmaster” clock or “Slave” clock. For power applications, Reason clocks support both the PTP Power Profile (IEEE C37.238:2017/2011) and the PTP Profile for Power Utility Automation (IEC 61850-9-3:2016).

To save time and reduce costs by avoiding the need to overlay a separate time-synchronizing network, SNTP/NTP and PTP can share the same physical links as IEC 61850, DNP3 over Ethernet, MODBUS, etc.

4.3 Parallel Redundancy Protocol (PRP)

The RT430 is the first Grandmaster clock to offer Parallel Redundancy Protocol (PRP). Profit from the high-availability, reliability, and security of your Ethernet network to distribute time accurately and economically over the same network used on your digital substation. The Parallel Redundancy Protocol (PRP) is in accordance with IEC 62439-3.

PRP may be use by any Ethernet protocol communication (including PTP, NTP, SNTP). When using PTP on PRP networks, the equipment can execute a BMC (Best Master Clock) algorithm in each port separately, calculating the link delays and responding to PTP management messages independently. Thus, besides the PTP redundancy on PRP networks, the RT430 compares the time quality between the two networks, to ensure the best time accuracy.

4.4 Stationary Mode

In mostly applications, the equipment providing the time synchronization must be in locked state. For this reason, the Stationary Mode allows the

equipment to be in a locked state even when receiving signals from a single satellite.

However, these two conditions are necessary to use the Stationary Mode:

- Stationary Mode can be used only when RT430/434 is in a fixed position (in a substation, for example). If the unit is moved from its position when operation in Stationary Mode, there will be loss of time accuracy.
- Before operating in Stationary Mode, RT430/434 must lock its sync receiving information from at least four satellites. This condition applies every time the unit is powered on.

4.5 Time Sync Flexibility

The RT430 and RT434 are equipped with multiple connector types, from isolated electrical ports to optical fibers. Mostly of the channels can be individually configured to generate the protocol needed, such as IRIG-B004, PPS, DCF77 and freely configurable low frequency pulses. Devices may be synchronized using LAN networks and integrated into the digital substation. Serial messages and datagrams are also available through a RS232 and RS422/485 serial port. This provides a highly versatile solution that can be standardized for multiple applications.

4.6 Environmental Robustness

With a robust design, RT430 and RT434 are in accordance with IEC 61010-1 and IEC 60255-27 standards, ensuring reliability and ruggedness even under harsh environments. Critical applications can benefit from the optional redundant power supply for even higher uptime and reliability. Every manufactured unit undergoes complete functional and stress tests to ensure the highest quality.

5 Functional Overview

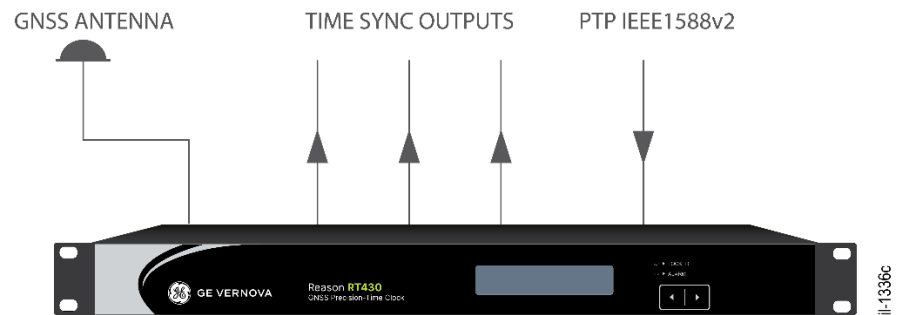


Figure 1: Functional Overview of RT430/434

6 Standards Compliance

The device has undergone a range of extensive testing and certification processes to ensure and prove compatibility with all target markets. A detailed description of these criteria can be found in the Technical Specifications chapter.

Compliance with the European Commission Directive and UK Conformity Assessed on EMC and LVD is demonstrated by self-certification against international standards.



- EMC Compliance: Compliance with IEC 60255-26:2013 was used to establish conformity.
- Product Safety: Compliance with IEC 61010-1:2010 was used to establish conformity.
- Protective Class: Protective Class I. This equipment requires a protective conductor (ground) to ensure user safety.
- Installation category: Compliance with IEC 61010-1:2010 Overvoltage Category II
- Environment: IEC 60068-2-1, IEC 60068-2-2, IEC 60068-2-30, IEC 60068-2-14, IEC 60255-21-1, IEC 60255-21-2. The equipment is intended for indoor use only. If it is required for use in an outdoor environment, it must be mounted in a specific cabinet or housing which will enable it to meet the requirements of IEC 60529 with the classification of degree of protection IP54.
- R&TTE Compliance: Radio and Telecommunications Terminal Equipment (R&TTE) directive 99/5/EC. Conformity is demonstrated by compliance to both the EMC directive and the Low Voltage directive, to zero volts.

Reason RT430/RT434

GNSS Precision-Time Clock

Chapter 2: Safety Information

This chapter provides information about the safe handling of the equipment. The equipment must be properly installed and handled in order to maintain it in a safe condition and to keep personnel safe at all times. You must be familiar with information contained in this chapter before unpacking, installing, commissioning, or servicing the equipment.

1 Health and Safety

Personnel associated with the equipment must be familiar with the contents of this Safety Information.

When electrical equipment is in operation, dangerous voltages are present in certain parts of the equipment. Improper use of the equipment and failure to observe warning notices will endanger personnel.

Only qualified personnel may work on or operate the equipment. Qualified personnel are individuals who are:

- Familiar with the installation, commissioning, and operation of the equipment and the system to which it is being connected.
- Familiar with accepted safety engineering practices and are authorized to energize and de-energize equipment in the correct manner.
- Trained in the care and use of safety apparatus in accordance with safety engineering practices
- Trained in emergency procedures (first aid).

The documentation provides instructions for installing, commissioning and operating the equipment. It cannot, however cover all conceivable circumstances. In the event of questions or problems, do not take any action without proper authorization. Please contact your local sales office and request the necessary information.

Each product is subjected to routine production testing for Dielectric Strength and Protective Bonding Continuity.

2 Symbols

Throughout this manual you will come across the following symbols. You will also see these symbols on parts of the equipment.



Caution: Refer to equipment documentation. Failure to do so could result in damage to the equipment



Risk of electric shock



Ground terminal. Note: This symbol may also be used for a protective conductor (ground) terminal if that terminal is part of a terminal block or sub-assembly.



Protective conductor (ground) terminal



Both direct and alternating current



Instructions on disposal requirements

The term 'Ground' used in this manual is the direct equivalent of the European term 'Earth'.

3 Installation, Commissioning and Servicing

3.1 Lifting Hazards

Many injuries are caused by:

- Lifting heavy objects
- Lifting incorrectly
- Pushing or pulling heavy objects
- Using the same muscles repetitively

Plan carefully, identify any possible hazards and determine how best to move the product. Look at other ways of moving the load to avoid manual handling. Use the correct lifting techniques and Personal Protective Equipment (PPE) to reduce the risk of injury.

3.2 Electrical Hazards



All personnel involved in installing, commissioning, or servicing this equipment must be familiar with the correct working procedures.



Consult the equipment documentation before installing, commissioning, or servicing the equipment.



Always use the equipment as specified. Failure to do so will jeopardize the protection provided by the equipment.



Removal of equipment panels or covers may expose hazardous live parts. Do not touch until the electrical power is removed. Take care when there is unlocked access to the rear of the equipment.



Isolate the equipment before working on the terminal strips.



Use a suitable protective barrier for areas with restricted space, where there is a risk of electric shock due to exposed terminals.



Disconnect power before disassembling. Disassembly of the equipment may expose sensitive electronic circuitry. Take suitable precautions against electrostatic voltage discharge (ESD) to avoid damage to the equipment.



NEVER look into optical fibers or optical output connections. Always use optical power meters to determine operation or signal level.



Testing may leave capacitors charged to dangerous voltage levels. Discharge capacitors by reducing test voltages to zero before disconnecting test leads.



If the equipment is used in a manner not specified by the manufacturer, the protection provided by the equipment may be impaired.



Operate the equipment within the specified electrical and environmental limits.



Before cleaning the equipment, ensure that no connections are energized. Use a lint free cloth dampened with clean water.



Integration of the equipment into systems shall not interfere with its normal functioning.



The functioning of the device has been certified under the circumstances described by the standards mentioned. Usage of the equipment in different conditions from the specified in this manual might affect negatively its normal integrity.



The equipment shall have all their rear connectors attached even if they are not being used, in order to keep their levels of ingress protection as high as possible



Never manipulate liquid containers near the equipment even when it is powered off.



Avoid modification to the wiring of panel when the system is running.

3.3 Fusing Requirements



A high rupture capacity (HRC) fuse type with a maximum current rating of 10 Amps and a minimum dc rating of 250 V dc may be used for the auxiliary supply (for example Red Spot type NIT or TIA). Alternatively, a miniature circuit breaker (MCB) of type C, 10 A rating, compliant with IEC 60947-2 may be used.



Reason devices contain an internal fuse for the power supply, which is only accessed by opening the product. This does not remove the requirement for external fusing or use of an MCB as previously mentioned. The ratings of the internal fuses are 2 Amp, type T, 250V.

3.4 Equipment Connections



Terminals exposed during installation, commissioning and maintenance may present a hazardous voltage unless the equipment is electrically isolated.



Tighten M3 clamping screws of heavy-duty terminal block connectors to a nominal torque of 1.0Nm. Tighten captive screws of header-type (Euro) terminal blocks to 0.5 Nm minimum and 0.6 Nm maximum.



Be careful, does not apply external voltage to TTL, AM and Serial outputs at the risk of causing irreversible damage to the equipment



Be careful when installing the antenna cable to RT43X. The cable may be too heavy to be supported by the antenna input connector only, damaging the equipment. Make sure the cable antenna is fixed in the rack (or other support) to minimize the weight load in the antenna input connector from RT43X.



Always use insulated crimp terminations for voltage and current connections.



Always use the correct crimp terminal and tool according to the wire size.



In order to maintain the equipment's requirements for protection against electric shock, other devices connected to the equipment shall have protective class equal or superior to Class I.



Ground the equipment with the supplied PCT (Protective Conductor Terminal).



Do not remove the PCT.



The PCT is sometimes used to terminate cable screens. Always check the PCT's integrity after adding or removing such ground connections.



The user is responsible for ensuring the integrity of any protective conductor connections before carrying out any other actions.



The PCT connection must have low-inductance and be as short as possible. For best EMC performance, ground the unit using a 10 mm (0.4 inch) wide braided grounding strap.



All connections to the equipment must have a defined potential. Connections that are pre-wired, but not used, should be grounded, or connected to a common grouped potential.



Pay extra attention to diagrams before wiring the equipment. Always be sure that the connections are correct before energizing the circuits.

3.5 Pre-energization Checklist



Check voltage rating/polarity (rating label/equipment documentation).



Check protective fuse or miniature circuit breaker (MCB) rating.



Check integrity of the PCT connection.



Check voltage and current rating of external wiring, ensuring it is appropriate for the application.

3.6 Peripheral Circuitry



Where external components such as resistors or voltage dependent resistors (VDRs) are used, these may present a risk of electric shock or burns if touched.



Operation of computers and equipment connected to RT43x under environmental conditions such as temperature and humidity that exceed the conditions specified in their respective manuals can cause malfunctioning or even irreversible damage to them or the nearby installation.



There might be situations in which the unit is operating within its environmental operational range, but the computers, equipment connected to them or nearby equipment are operating outside their operational range. That situation can cause malfunctioning and/or irreversible damage to those devices. In that occasion the communication to the Reason equipment might be compromised but its operational and safety capacities will not be affected.

3.7 Upgrading/Serviceing



Do not insert or withdraw modules, PCBs or expansion boards from the equipment while energized, as this may result in damage to the equipment. Hazardous live voltages would also be exposed, endangering personnel.



Internal modules and assemblies can be heavy and may have sharp edges. Take care when inserting or removing modules into or out of the IED.

4 Decommissioning and Disposal



Before decommissioning, completely isolate the equipment power supplies (both poles of any dc supply). The auxiliary supply input may have capacitors in parallel, which may still be charged. To avoid electric shock, discharge the capacitors using the external terminals before decommissioning.



Avoid incineration or disposal to water courses. Dispose of the equipment in a safe, responsible and environmentally friendly manner, and if applicable, in accordance with country-specific regulations.

Reason RT430/RT434

GNSS Precision-Time Clock

Chapter 3: Hardware Design

This chapter demonstrates the main hardware characteristics from RT430 and RT434.

1 Front View

The front panel of the RT430/RT434 comprises a LCD display, two indicators and buttons to navigate through the screen. The figures below show the front view of the RT430 and RT434.



Figure 2: Front view of RT430



Figure 3: Front view of RT434

The RT430/434 have an LCD display (20 columns x 2 lines) for time monitoring and network setup. The display's first screen shows temporal reference information: date and time, time zone and the number of monitored satellites.

By navigating through the display using the buttons (arrows pointing right and left), it is possible to check the configuration of the equipment's Ethernet networks. IP addresses, network mask, gateway, broadcast and DNS server are shown for each network.

The LOCKED indicator shows if the equipment is synchronized with time reference from satellites. When the ALARM indicator is on, the equipment is not operating and operator attention is required.

2 Rear View

The rear panel of the RT430/434 comprises:

- Two power supplies (one is optional), AC/DC high voltage or DC low voltage;

- Two TTL electrical outputs (Euro Type connectors) for synchronization, one of them insulated;
- Two TTL electrical outputs (BNC connectors) for synchronization, one of them insulated;
- Two open collector outputs for time synchronization;
- Locked contactor relay (alarm) and one event input with TTL level;
- One amplitude-modulated output for IRIG-B124 signal;
- Two optical outputs for synchronization using ST connectors;
- RS232 and RS422/485 serial ports for time synchronization via pulses or datagrams;
- Two Ethernet network communication ports for the RT430 and four Ethernet ports for the RT434;
- GNSS antenna input.

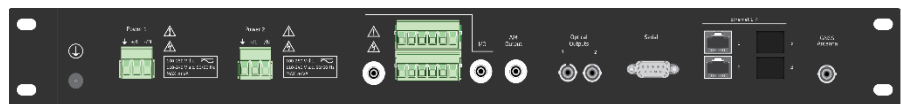


Figure 4: Rear view of RT430

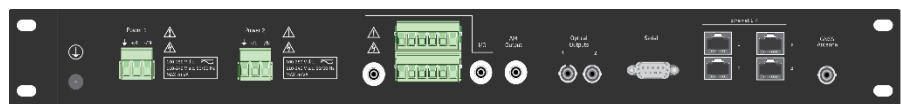


Figure 5: Rear view of RT434

3 Network Ports

Each network interface presents the following features depending on the equipment version:

1. Monitoring and configuration;
2. NTP/SNTP synchronization protocols;
3. IEEE 1588 PTP synchronization protocol;

The RT430 also has the PRP Parallel Redundancy Protocol available for redundant network architectures.

4 Power Supply

Apart from the main power supply, there is a redundant power supply available for RT430 and RT434. Each power supply can have the nominal voltage ranges as listed below:

1. 100-240Vac, 110-250Vdc;
2. 24-48Vdc.

Note the redundant power supply is independent from the main one. Please refer to technical specification for the operating ranges.

Reason RT430/RT434

GNSS Precision-Time Clock

Chapter 4: Installation

The RT430/434 is ruggedized and specifically designed for operation and to be part of the large scale electrical fixed installations, as electrical power generation installations, electrical substations and electrical utilities control systems.

1 Unpacking

Unpack the unit carefully and make sure all the accessories and cables are put aside so they will not be lost.

Check the contents against the packing list that goes with the product. If any of the content listed is missing, please contact GE Vernova (see contact information in Maintenance chapter).

Examine the unit for any shipping damage. If the unit is damaged or fails to operate, notify the shipping company without delay. Only the consignee (the person or company receiving the unity) can file a claim against the carrier for shipping damage.

It is recommended to keep the original packing materials for possible transport in the future.

1.1 Normal Use of the Equipment

In order to maintain the equipment integrity, levels of protection and assure user safety, the RT430/434 must be installed in an enclosed panel with recommended ingress protection rating of IP54 or above.

The enclosing panel must ensure that the equipment rear connections and sides are unexposed and protected against impact and water, whilst maintaining adequate temperature and humidity condition for the devices. Furthermore, the equipment must have all their rear connectors attached, even if not being used, to keep their levels of ingress protection as high as possible.

During the normal use of the device only the front panel will be accessible.

1.2 External Indications

Connector descriptions are located in the upper side of the equipment, while the serial number and part number are shown on a label positioned on the right side.

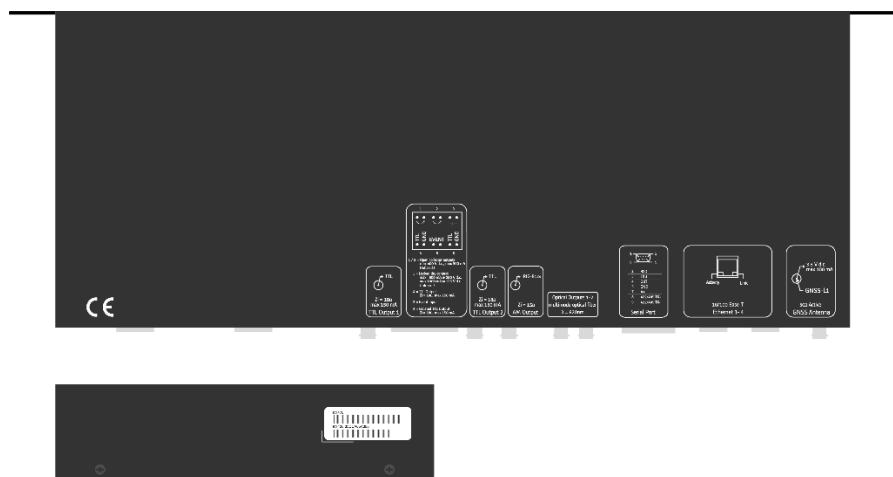


Figure 6: Location of Serial number, part number and outputs description.

2 Mounting

The equipment has been designed to be mounted in a standard 19-inch rack using four M6x15 screws.

Keep adequate clearance for all connections. In particular, the optical fiber cables should be installed in compliance with the 30 mm minimum bending radius.

For more information regarding the equipment dimensions, refer to the Technical Specification chapter.

2.1 Power Supply

The unit can be powered from a DC or AC power supply within the limits specified. If the redundancy power supply was ordered, the two power supplies should be provided independently to ensure operation if one of them is interrupted.

All power connections must use insulated flameproof flexible cable with a 1.5 mm² cross section, 70 °C thermal class, and 750 V insulation voltage. To reduce the risk of electrical shock, pre-insulated tubular pin terminals should be used on the ends of the power connections.

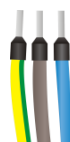


Figure 7: Pre-insulated tubular pin terminals

The pin terminals must be completely inserted into the connector supplied with the unity so that no metallic parts are exposed, according to the figure below.

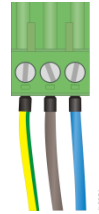


Figure 8: Supply connector assembly

A 1.5 mm² ground lead must be connected to the terminal marked with the protective ground symbol for EMC purposes.

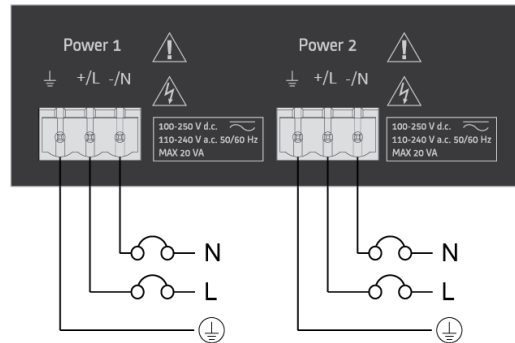


Figure 9: RT430/RT434 Power Connection

For AC power connection, the phase conductor must be applied to terminal (+/L), neutral conductor to terminal (-/N) in each of the supply terminals identified, Power 1 and Power 2.

For DC power connection, the positive line should be applied to terminal (+/L), negative to terminal (-/N) in each of the supply terminals identified, Power 1 and Power 2.

For compliance with IEC 61010, install a suitable external switch or circuit breaker in each current-carrying conductor of RT430/434 power supply; this device must interrupt both the hot (+/L) and neutral (-/N) power leads. An external 10 A, category C, bipolar circuit-breaker is recommended. The circuit breaker should have an interruption capacity of at least 25 kA and comply with IEC 60947-2. The switch or circuit-breaker must be suitably located and easily reachable, also it must not interrupt the protective ground conductor.

2.2 Grounding (Earthing)

To ensure proper safety and performance, the case protective ground connection must be grounded to the panel using a 10mm width copper strap (minimum) with M6 ring lug connector.

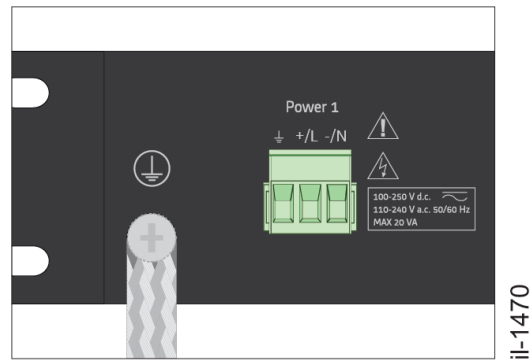


Figure 10: RT430/434 Grounding Strap

2.3 GNSS Antenna Terminal

A 3.3-Volt active GNSS antenna (100 mA max loading) must be connected to the antenna input terminal when satellites are being used as time reference.

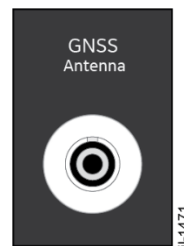


Figure 11: GNSS antenna connector

If the GNSS antenna is connected and it is possible to receive signal from at least 4 satellites the LOCKED indicator will start to blink after a couple of seconds, indicating that the internal time-base is being synchronized with the satellites. The LOCKED indicator will stop blinking and will remain lit as soon as maximum accuracy is achieved. This process may take several minutes if the equipment was transported for more than a few hundred kilometers or was unpowered for many weeks. The dry-contact LOCKED in the rear panel opens when maximum accuracy is achieved.

The antenna must be mounted outdoors, in a vertical position, with an unobstructed view of the sky. The antenna should be placed above the height of the building as much as possible. A partially obstructed sky view will compromise the unit's performance.

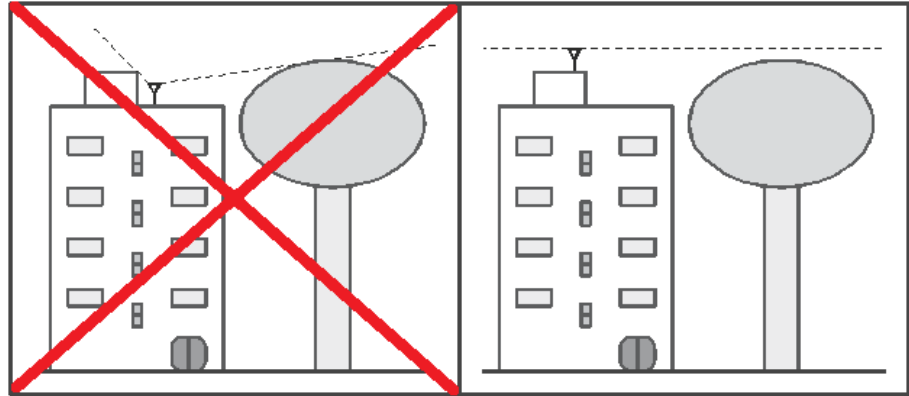


Figure 12: Recommended position for installing the GNSS Antenna

The antenna should not be located under overhead power lines or other electric light or power circuits, or from where it can fall onto such power lines or circuits.

An antenna mast of roof-mounting-kit and any supporting structure must be properly grounded to provide protection against voltage surges and built-up static charges. It is recommended the use of a surge arrester for the entire wiring where there is external antenna cabling.

The antenna must be connected to the unit by using a coaxial cable with a 50 Ω impedance. The antenna cable should be routed through a conduit, shielded from rain and/or solar radiation. The conduit should not be shared with any power circuits.

It is recommended to use a 3/4 PVC conduit, threaded on one end. To install it, cut down to the intended size and screw the antenna in the conduit. The conduit can be fixed on the wall, so that the antenna is above the wall limit and free from lateral obstacles, as shown in the next figure.

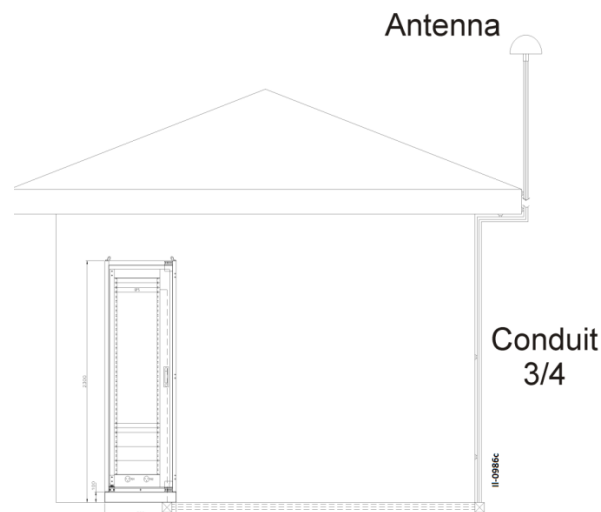


Figure 13: Recommended position GNSS Antenna conduit installation

Cables with lengths ranging from 25 m (82 ft) to 100 m (328 ft) can be ordered from GE Vernova. Be careful when installing the antenna cable to RT43X. The cable may be too heavy to be supported by the antenna input connector only, damaging the equipment. Make sure the cable antenna is

fixed in the rack (or other support) to minimize the weight load in the antenna input connector from RT43X.

For use of antennas and cables from other manufacturers, contact GE Vernova for evaluation.

The antenna cable affects the unit's performance in two distinct ways: satellite signal attenuation and propagation delay.

2.4 TTL Electrical Outputs

The RT430/434 has 4 electrical outputs, 2 screw connectors, and 2 BNC connectors. One output of each connector type is insulated.

The type of signal at each output can be configured through a Web Interface to generate IRIG-B004, DCF77, 1PPS, 1PPM, 100PPS, or any custom-defined low frequency, from 1 pulse-every-two-seconds to 1 pulse-per-day. In addition, it is possible to configure the outputs to generate daily set-time pulses. The polarity of the signal and the pulse width can also be configured.

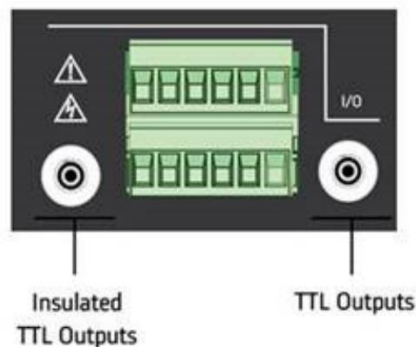


Figure 14: TTL electrical outputs

More than one device can be connected in parallel from one TTL output. The maximum number of devices that can be connected to the TTL output depends on the current that each device's input uses. As the maximum current supplied from each TTL output is 150mA, the sum of the currents from all devices connected cannot exceed this value (cable resistance should be considered). The TTL voltage level is 5V.

Electrical cable length should not exceed 100m. To minimize EMC effects in IRIG-B signals, the use of fiber-optic cable is recommended for distances greater than 3 m.

For details on the configuration of TTL-Level electrical outputs, refer to the Configuration chapter.

See the Technical Specification chapter for more description of signal levels and maximum ratings.

2.5 Open-Collector Electrical Outputs

The unit has 2 open-collector electrical outputs, available for customized time synchronization with DC level. The electrical cable length should not exceed 100m.

The type of signal at each output can be configured through a Web Interface to generate IRIG-B004, DCF77, 1PPS, 1PPM, 100PPS, or any custom-defined low frequency, from 1 pulse-every-two-seconds to 1 pulse-per-day. In addition, it is possible to configure the outputs to generate daily set-time pulses. The polarity of the signal and the pulse width can also be configured.

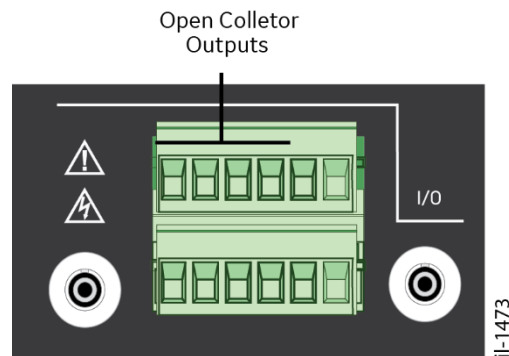


Figure 15: Open collector electrical outputs

The open-collector outputs require the use of an external resistor properly sized to limit current to a value below 300 mA.

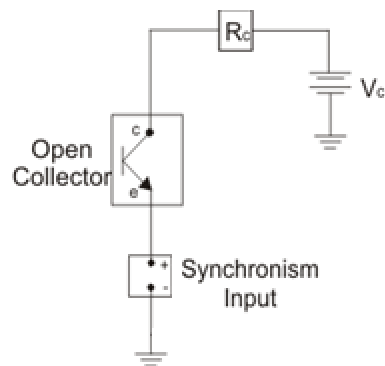


Figure 16: Connection diagram of the open-collector electrical outputs

To scale the resistor use the relationship:

$$R_c \geq \frac{V_c}{0.3}$$

Where V_c is the DC external voltage to be switched by the open-collector output.

The resistor power should be adequate for the voltage and current values to be switched, i.e.

$$P_c \geq 1.2 \cdot \frac{V_c^2}{R_c}$$

Do not connect the open-collector electrical outputs without a properly sized external resistor or another appropriate mechanism to limit current. See the Technical Specification chapter for a description of signal levels and maximum ratings.

2.6 Optical Outputs

RT430/434 has 2 outputs for multimode optical fiber. The length of fiber-optic cables should not exceed 2 km.

The type of signal at each output can be configured through a Web Interface to generate IRIG-B004, DCF77, 1PPS, 1PPM, 100PPS, or any custom-defined low frequency, from 1 pulse-every-two-seconds to 1 pulse-per-day. In addition, it is possible to configure the outputs to generate daily set-time pulses. The polarity of the signal and the pulse width can also be configured.

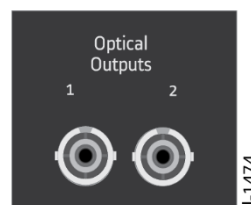


Figure 17: Optical outputs

See the Technical Specification chapter for optical outputs technical information.

2.7 Amplitude Modulated Output

The RT430/434 has one amplitude-modulated output, which generates an IRIG-B124 signal. Use coaxial cables with an impedance of 50 Ω and a BNC connector on this output. See the Technical Specification chapter for the signal levels description.



Figure 18: Amplitude modulated output

2.8 Serial Port (RS232, RS422/485)

The serial port is compatible with the RS232 and RS422/485 standard (DTE pin-layout). The RS422/485 is capable of synchronizing up to 32 devices.



Figure 19: Serial port RS232 and RS422/485

Table 1: Serial port pinout

DB9 male	Signal
1	-
2	TXD (used to send the datagram)
3	RXD
4	OUT (RS232 level output with user-programmable signal)
5	GND
6	-
7	V+ (RS232 level voltage reference of the internal converter)
8	422/485 TX+
9	422/485 TX-

The bit-rate, format (number of data bits, parity, number of stop bits) and datagram type can be configured using the Web Interface, as well as the type of signal transmitted by the pin OUT (pin 4).

Pins 2, 3 and 5 are used for the RS232 interface.

Pins 8 and 9 are used for the RS422 or RS485 interface.

For serial port configuration, see the Configuration chapter.

For existing datagrams details, see Appendix.

2.9 Dry-Contact Relay

The RT430/434 has 1 dry-contact that can be used to remotely signal the locked state of the unity and to alarm if there is no power on the unit.

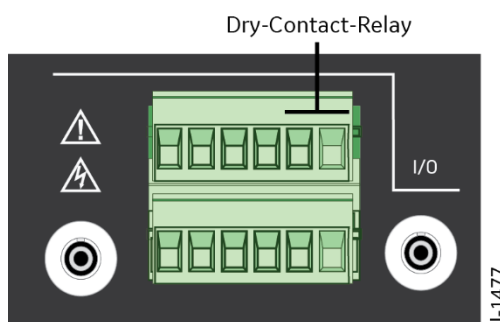


Figure 20: Dry-contact relay

When the unit is powered up, the dry-contact relay is normally closed.

When the equipment enters in the locked state, the dry-contact will open.

The dry-contact closes after 10 seconds later (holdover ensures 1 μ s accuracy) in case the unit lost satellite signals as reference, or immediately if none power supply is available.

See the Technical Specification chapter for information on switching capacity limitations.

2.10 Event Input

The RT430/434 has 1 input to detect TTL-Level external events. This input may be used to verify the PTP signal quality when RT430/434 synchronizes another clock using PTP. Thus, the TTL output from the PTP Slave clock may be connected to the event input from RT430/434 in order to measure the signal quality.

The electrical output from the PTP Slave clock should be configured to send pulses in a time frequency and an event will be registered in a log file containing the pulse timestamp for each received pulse. The input accuracy is in the magnitude of ns.

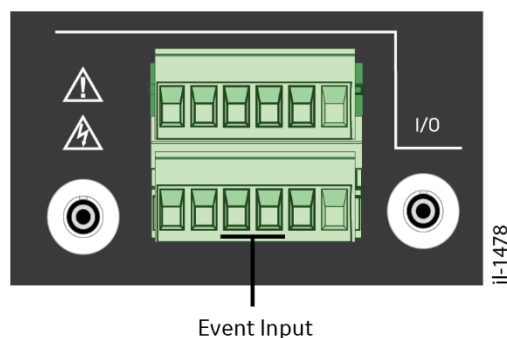


Figure 21: Event input

2.11 Euro Type Connections

The following information is available in the top of the unit, but if the equipment is already installed in the panel, it may be useful when handling the Euro Type connector for TTL outputs, Open collector, Locked relay and event input.

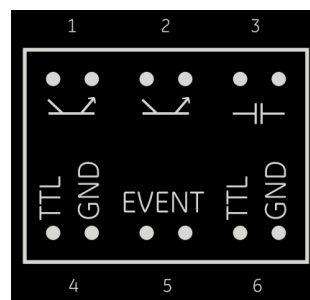


Figure 22: Euro Type label for connections

- Numbers 1 and 2: Open collector outputs;

- Number 3: Locked (dry contact) relay;
- Number 4: Isolated TTL output;
- Number 5: Event input;
- Number 6: Non-isolated TTL output.

3 Ethernet Communication

The RT430 has 2 Ethernet 10/100BaseT (auto-negotiation) communication interfaces with RJ45 connectors, and the RT434 has 4 Ethernet 10/100BaseT (auto-negotiation) ports. When a CAT5 cable with RJ45 connector is plugged in each port, the LINK led will indicate that the cable is transmitting signal, and the ACTIVITY led blinks when there is data exchange.

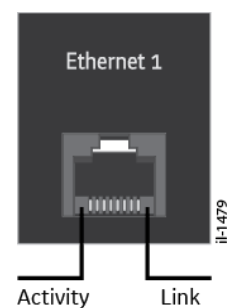


Figure 23: Electrical communication interface via Ethernet network

3.1 Factory default settings

Table 2: Ethernet port 1 default settings

IP Address	192.168.0.199
Netmask	255.255.255.0
Broadcast	192.168.0.255

Table 3: Ethernet port 2 default settings

IP Address	192.168.1.199
Netmask	255.255.255.0
Broadcast	192.168.1.255

Table 4: Ethernet port 3 default settings (RT434)

IP Address	192.168.2.199
------------	---------------

Netmask	255.255.255.0
Broadcast	192.168.2.255

Table 5: Ethernet port 4 default settings (RT434)

IP Address	192.168.3.199
Netmask	255.255.255.0
Broadcast	192.168.3.255

The factory's default port to connect to the Gateway is the Ethernet 1. The factory default settings of the Gateway and DNS Server are:

Table 6: Gateway and DNS Server default settings

Gateway (Ethernet 1)	192.168.0.254
Server DNS	192.168.0.254

The Ethernet parameters can be configured through the Web Interface.

3.2 Network port and communication protocols

To ensure unrestricted access to communication via Ethernet network, the following ports and protocols should be enabled:

Table 7: Network port and communication protocols

Port	Protocol	Description
80	TCP/IP	Remote access via Web
123	UDP	NTP/SNTP Time synchronization
161	UDP	SNMP for equipment monitoring
319	UDP	Sending event messages PTP to synchronize
320	UDP	Sending general messages via PTP to synchronize
443	HTTPS	Establishing a safe connection via Web interface

3.3 Equipment access

The Web Interface is designed for configuring and monitoring the unit through a web browser, if the unit is accessible from a local network. To use all features through the Web Interface, make sure to use one of the following web browsers:

- Internet Explorer version 7.0 or newer.
- Mozilla Firefox version 3.0 or newer.
- Google Chrome

Connect to the Web Interface by entering the unit IP address into the address field of your web browser. After the page is loaded, the unit's Web Interface will open, allowing the user to operate, monitor, and configure it.

4 Powering Up

Before energizing the unit, familiarize yourself with all the risks and attention indicators in the equipment frame.

- Connect the power supply (including the ground lead) to the appropriate terminals.
- The unit will perform a self-test procedure, and the Alarm indicator will remain lit.
- At the end of the self-test, the equipment will perform initialization of the GNSS receiver. At the end of approximately one minute, the Alarm indicator will go out and information will be shown in the equipment's display. If Alarm indicator remains on, the unit will not be operating and it will require attention by the user.
- To turn off the unit, switch off the external switch or circuit breaker. The unit will record the time, date, satellite orbits parameters, and internal oscillators drift estimates in non-volatile memory to improve accuracy and reduce the time to synchronize with satellites in the next energizing process. Also, all indicators LEDs will turn off.

In case the unit does not behave in a way here described, carefully check all power and signal connections. See Maintenance chapter for additional suggestion for problem diagnosis.

5 Preventive Maintenance Actions

In view of the critical nature of the application, GE products should be checked at regular intervals to confirm they are operating correctly. GE products are designed for a life in excess of 20 years.

The devices are self-supervising and so require less maintenance than earlier designs of protection devices. Most problems will result in an alarm, indicating that remedial action should be taken. However, some periodic tests should be carried out to ensure that they are functioning correctly and that the external wiring is intact.

It is the responsibility of the customer to define the interval between maintenance periods. If your organization has a Preventative Maintenance Policy, the recommended product checks should be included in the regular program. Maintenance periods depend on many factors, such as:

- The operating environment;
- The accessibility of the site;
- The amount of available manpower;
- The importance of the installation in the power system;
- The consequences of failure.

5.1 Preventive Actions

For optimum performance of Reason RT430/434, perform the following preventive maintenance procedures and actions:

Keep temperature and humidity at adequate levels inside the panel. The American Society of Heating, Refrigerating, and Air Conditioning Engineers (ASHRAE) recommends operating network equipment within the following ranges of temperature and relative humidity (see the ASSHRAE TC9.9 “2011 Thermal Guidelines for Data Processing Environments – Expanded Data Center Classes and Usage Guidance”).

- Temperature within 18° C to 27° C (64.4° F to 80.6° F)
- Relative humidity less than 60%
- Dew point within the range of 5.5° C to 15° C (41.9° F to 59.0° F)

Operating within this range supports the highest degree of equipment reliability, even though the equipment data sheets may state wider ranges of minimum and maximum temperature and humidity (for example, -40° C to 55° C and 5% to 95% RH). Continuous equipment operation at the minimum and maximum limits is not recommended.

Keep panel sealed to avoid dust and/or animals and insects.

Inspect the installation site for moisture, loose wires or cables, and excessive dust. Make sure that airflow is unobstructed around the device and into the air intake vents.

It is recommended weekly or every two weeks to access the web interface area of the unit and check the equipment details in Status area. See Operation chapter for further details regarding the equipment status.

If any abnormal conditions are observed, refer to Maintenance chapter or contact the technical support team to obtain the suitable instructions to deal with the issue.

Reason RT430/RT434

GNSS Precision-Time Clock

Chapter 5: Operation

This chapter introduces the Local and Remote Interface available for RT430/434.

1 Local Interface (HMI)

The RT430/434 front panel consists of a LCD display, two indicators and buttons to navigate through the screen. The figure below illustrates the equipment’s front view.



Figure 24: Local Interface from RT430 and RT434

The RT430/434 has an LCD display (20 columns x 2 lines) for time monitoring and network setup. The display's first screen shows temporal reference information: date and time, time zone and the number of monitored satellites.

By navigating through the display using the buttons (arrows pointing right and left), it is possible to check the configuration of the equipment's Ethernet networks. IP addresses, network mask and broadcast address are shown for each Eth port, plus the default gateway and DNS server from the equipment. The following illustration presents the possible menu screens for the RT430. The RT434 menu has the same screens as the RT430, but informing about all 4 Ethernet ports.

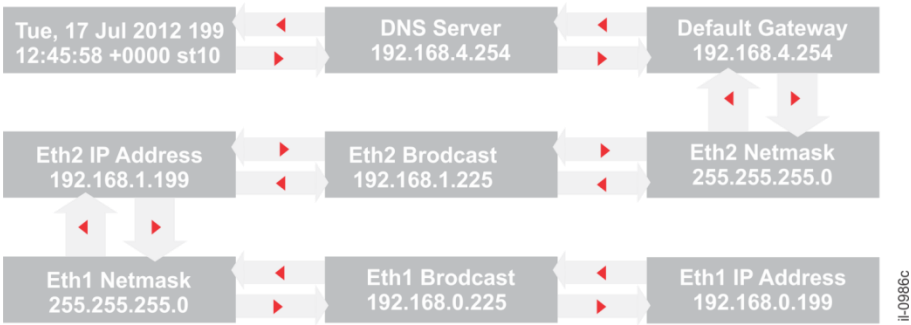


Figure 25: Navigating the RT430's local monitoring display

The Locked indicator shows that unit is synchronized with time references from satellites. This indicator blinks when the unit is searching for orbit data from satellites, which is a common situation if the unit has been moved over long distances or has been out of operation for a long period. This indicator will turn off a few seconds after the external reference is lost.

The Alarm indicator will light up for a brief period while the unit powers up. After concluding the initialization, the unit will start operating and this indicator should turn off. If Alarm indicator remains on, the unit is not operating normally and will require user attention.

2 Web Interface (Remote Access)

To access RT43X web interface either a HTTP or HTTPS connection must be established through a web browser. For HTTPS connections, RT43X supports TLS 1.0, which have been deprecated by latest web browser releases. Thus, refer to web browsers versions supporting TLS 1.0:

- *Google Chrome v90 or previous.*
- *Microsoft Edge v90 or previous.*
- *Mozilla Firefox v77 or previous.*

The RT430/434 has a Web Interface for monitoring and configuring the unit. This section describes how to monitor the RT430/434 status in real time, check general system information and to log external timestamps pulses.

To connect to the Web Interface, enter the unit Ethernet port IP address into the address field of a web browser. For information on factory defaults for the Ethernet port, see the Installation chapter. If the unit is not using factory default settings, the current IP address can be obtained by the local HMI (LCD display and keys).

A start page containing the unit status information opens the Web Interface. The remaining monitoring and configuring sections are on a menu on the left. To access them, click the desired menu item.

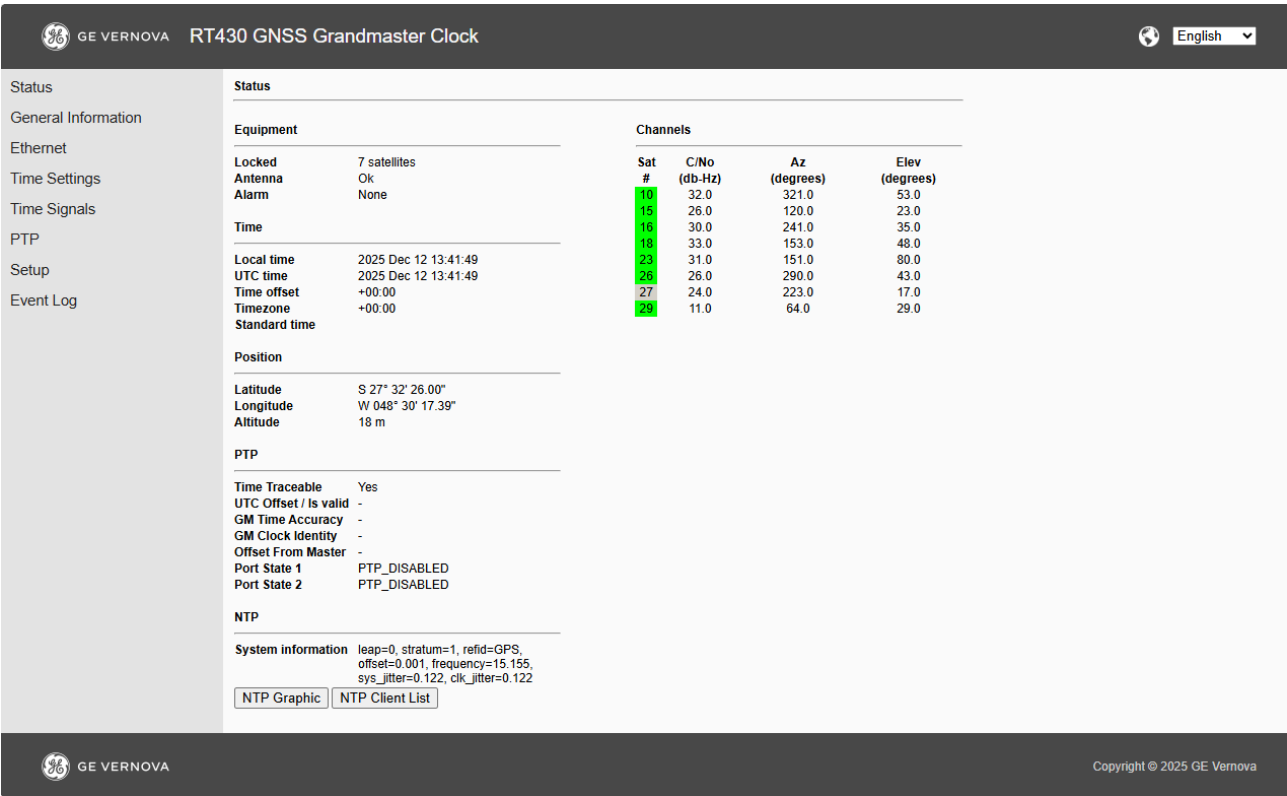


Figure 26: RT430 Web Interface

2.1 Web Interface Language

The Web Interface is available in five different languages: English, French, Spanish, Portuguese, Russian. To choose the language refer to the globe figure in the upper-right corner.

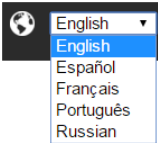


Figure 27: Languages available in the Web Interface

3 Monitoring Menus – Web Interface

The following sections will describe the monitoring menus from the Web Interface:

- Status: monitoring the status of the unit in real time.
- General Information: information of the unit system.
- Event Log: timestamp pulses received from another time source.

3.1 Status

The section Status of Web Interface, as shown below, allows monitoring status information of the unit in real time.

Status					
Equipment		Channels			
Locked	6 satellites	Sat #	C/No (db-Hz)	Az (degrees)	Elev (degrees)
Antenna	Ok	6	35.0	100.0	47.0
Alarm	None	12	36.0	220.0	39.0
Time		2	28.0	34.0	53.0
Local time	2016 Nov 29 14:48:51	24	41.0	240.0	71.0
UTC time	2016 Nov 29 16:48:51	19	37.0	143.0	33.0
Time offset	-02:00	17	33.0	137.0	14.0
Timezone	-03:00				
Daylight saving time					
Position					
Latitude	S 27° 34' 36.52"				
Longitude	W 048° 31' 38.22"				
Altitude	15 m				
PTP					
Time Traceable	Yes				
UTC Offset / Is valid	36 s / Yes				
GM Time Inaccuracy	60 ns				
GM Clock Identity	00:50:c2:ff:fe:69:bb:bb				
Port State 1	PTP_MASTER				
Port State 2	PTP_MASTER				
NTP					
System information		leap=0, stratum=1, refid=GPS, offset=-0.000, frequency=11.944, sys_jitter=0.122, clk_jitter=0.122			
NTP Graphic NTP Client List					

Figure 28: Section to monitor the status of the unit in the Web Interface

The unit status information is grouped into areas, as follows:

- **Equipment:** shows operational information of the unit.
 - **Locked:** indicates if the unit is in the locked state or not. If yes, the number of monitored satellites is indicated.
 - **Antenna:** indicates if the GNSS antenna is properly connected to the unit.
 - **Alarm:** indicates if the unit is presenting internal failure.
- **Time:** presents the local time, UTC, off-set and time zone.
- **Position:** latitude, longitude and altitude information.
- **PTP:** shows status from PTP protocol, the time inaccuracy, GrandMaster Identity and the state from each port.
- **NTP:** presents the NTP information, including NTP stratum. The NTP graphic illustrates the NTP offset time and the NTP Client List displays all NTP clients that have recently sent requests to RT430/434. NTP Clients will appear up to 1 hour after from last NTP request sent. Both NTP Graphic and NTP Client List does not have automatic refresh.
- **Channels:** monitored satellites information (number, phase noise, azimuth and elevation). The background of Satellite number (Sat #) is green when receiving the health ephemeris data. A grey background means the satellite is not healthy by the moment, and it is not been used as reference.

3.2 General Information

The section General Information of the Web Interface displays system information of the unit.

General Information		
Firmware version	rt430-08A00.00	
Hardware version	RT5	
Serial number	44556677	
Mac address Ethernet 1	00:50:C2:69:BB:BB	
Mac address Ethernet 2	00:50:C2:69:BB:BC	
Product Key	BBAB8HGF*****BBD951DJ	
Ethernet 1	Feature	Status
	NTP	Enabled
Ethernet 2	PTP	Enabled
	NTP	Enabled
PRP	PTP	Enabled
	PRP	Enabled

Figure 29: Section to visualize general information of the system

The system information is as follows:

- Firmware Version: presents the current firmware version of unit.
- Hardware Version: presents the hardware version of unit.
- Serial Number: presents the serial number of unit.
- MAC Address Ethernet 1/4: presents the MAC address of each Ethernet port.
- Key: partially displays the equipment key according to the cortec.
- Ethernet Ports: presents the status of NTP and PTP.
- PRP: presents the status of PRP (RT430 only).

3.3 Event Log

The section Event Log from the Web Interface allows monitoring external timestamp pulses received from another time source. The timestamp frequency registered in log files is according to the pulse frequency received through the event input.

Event Log

Last Events

Timestamp

Update

Clear

Timestamps log file

Click the button below to download the timestamps log from event input.

Download

Figure 30: Section of Web Interface to monitor timestamps of event input

- Last Events: In the Timestamp area, it is possible to view the last ten timestamps from a signal received through the event input. The update of timestamps is not automatic. To view them, click the button <Update>.
- Timestamps Log file: a .txt format file, containing the timestamps registered in the unit. By clicking <Download> a window will open to save the file in a directory on the computer.

The RT430/434 event input can register up to 3600 timestamps.

Reason RT430/RT434

GNSS Precision-Time Clock

Chapter 6: Configuration

This chapter describes how to configure the RT430/434.

1 Web Interface

The Reason RT430/434 GNSS Precision-Time Clock has a Web Interface for configuring network parameters, time parameters, time synchronization outputs and PTP standard, updating firmware, changing key, controlling access and manipulating configurations.

To connect to the Web Interface, enter the unit Ethernet port IP address into the address field of a web browser. For information on factory default settings of the Ethernet ports, see Installation chapter. If the unit is not using factory default settings, the current IP address can be obtained by the local HMI (LCD display and keys).

A start page containing the unit status information opens once the Web Interface is accessed. The remaining monitoring and configuring sections are on a menu on the left. To access them, click the desired menu item. The configuring sections are:

- Ethernet: allows configuring the network parameters.
- Time Settings: allows configuring the time parameters.
- Time Signals: allows configuring signals sent from outputs.
- PTP: allows configuring PTP clock parameters in accordance with IEEE 1588.
- Setup: allows manipulating configurations, changing access control and key, and updating firmware.

1.1 User Name and Password

The configuration sections should be edited one by one and at the end of each section, it is necessary to transmit the changes made to the unit. Otherwise, the changes will not be saved. When transmitting changes to the unit, username and password will be required. Factory default username and password are:

Table 8: Factory default username and password

User name	configuration
Password	1234

1.2 Sending Configuration

To send the new configuration to the equipment, click on the <Apply> button. Then the username and password of the equipment will be requested.

Once both entered, click on login and the equipment will update its configuration. A message will be displayed informing the status of the update.

In case the new configuration is not transmitted to the unit, the changes will not be saved and will be discarded once the Web Interface is closed.

2 Ethernet

The Ethernet section of the Web Interface allows enabling the PRP (only in RT430) and configuring network parameters of Ethernet ports 1, and 2, gateway and DNS. RT434 will display four Ethernet ports.

Figure 31: Section to configure network parameters of the unit

2.1 PRP (only in RT430)

To enable the Parallel Redundancy Protocol check the PRP Enabled box, as shown below, and click on the <Apply> button. When using PRP, the Ethernet port 2 uses the same Network parameters from Ethernet port 1.

For this reason, the Ethernet 2 configuration keeps disabled when PRP is enabled.

The screenshot shows the 'Ethernet' configuration window. At the top, 'PRP' is enabled with a checked checkbox. Below this, 'Ethernet 1' is configured with a fixed MAC address of 00:50:C2:69:BB:BB and input fields for IP address (192.168.0.10), Network mask (255.255.255.0), and Broadcast (192.168.0.255). 'Ethernet 2' is shown as 'Config. disabled'. The 'Default Gateway' section has an IP address of 192.168.0.1 and the Port set to 'Ethernet 1'. The 'DNS Server' section has an IP address of 192.168.0.1.

Figure 32: Enabling the PRP redundancy

2.2 Ethernet Ports

The Ethernet ports allow communication via TCP/IP or UDP/IP networks.

- MAC Address: informs the MAC address of the network port.
- The IP Address field allows entering the IP address of the network port (only decimal numbers).
- The Network Mask field allows entering the network mask from the network to which the unit will be connected (only decimal numbers).
- The Broadcast field allows entering the subnet address to which the unit will be connected (only decimal numbers).

2.3 Default Gateway

The gateway configuration allows RT430/434 to communicate with other devices connected to a local subnet.

- The IP Address field allows entering the network port IP address of the unit (only decimal numbers).
- The field Port allows choosing the communication port to be used as gateway

2.4 DNS Server

The DNS server configuration allows the RT430/434 to communicate with the DNS server from a local subnet. The IP Address field allows entering the IP Address of the network's name server (only decimal numbers).

2.5 Ethernet - Configuration Summary

The table below presents all configurable network parameters and its possible values and variables.

Table 9: Summary of configurable network parameters

Ethernet Ports		
MAC Address	00:00:00:00:00:00	Not configurable
IP Address	0.0.0.0	Only decimal numbers
Network Mask	0.0.0.0	Only decimal numbers
Broadcast	0.0.0.0	Only decimal numbers
Gateway		
IP Address	0.0.0.0	Only decimal numbers
Port	Ethernet port 1, 2, 3* or 4*	Selectable
DNS Server		
IP Address	0.0.0.0	Only decimal numbers

* only in RT434

3 Time Settings

The Time Settings section of the Web Interface allows configuring time parameters.

Time Settings

Timezone

-03

h

00

m

☒ DST

Start

00

h

00

m

Third

Sunday

October

End

00

h

00

m

Third

Sunday

February

☐ NTP - Send local time

Figure 33: Section to configure time parameters

3.1 Time Parameters

- The field Timezone allows configuring the time zone of the unit, and converting UTC time to local time. Half hour time zones are supported.
- The field DST, when enabled, allows configuring the beginning and the end of Daylight Saving Time.
- When the option NTP – Send local time is selected, the local time in accordance with timezone and DST configuration is sent through NTP protocol. If this option is unselected, the UTC is sent.

3.1.1 Leap Second

The RT430/434 has built-in support for leap seconds, whenever indicated by the GNSS (when operating as GNSS Clock) or by PTP Grandmaster (when operating as PTP Slave).

In both cases, the timestamp will be 23:59:60 at the moment the second increases (leap). In other words, while the last second of a normal day is 23:59:59, the last second of a day with Leap Second is 23:59:60.

This can also be verified in the Web Interface, under the NTP information of the Status section. The first field, "leap", indicates whether a leap second will be applied at the end of the day. Its standard value is 0 (normal, leap second warning). This field has the value 1 if the last minute of the day has 61 seconds; or the value 2 if the last minute of the day has 59 seconds. So, from the beginning of the day that will take place the Leap Second field will have a value of 1 or 2; after the application of the Leap Second this field value is back to its normal value 0.

Besides the Web Interface, leap second treatment is also stored on the equipment's event log, and may be checked after the occurrence of a leap. The processing and treatment of the Leap Second happens automatically and may not be disabled.

3.2 Network Time Protocol (NTP)

The NTP/SNTP is activated by default if the licensing was ordered (the General Information section displays if NTP is enabled or disabled). The NTP/SNTP operates at unicast (client/server) mode, in accordance with NTP v2 (RFC 1119), NTP v3 (RFC 1305)

NTP v4 (RFC 5905) and SNTP (RFC 1769/2030/4330).

After initiating the clock, the NTP stratum is set to 16 and the Leap Second information is set as 3 (unknown). To inform the clients NTP when the time is global, the stratum level is set to 1 when the clock has its antenna connected and start tracking the satellites. By this time, the Leap Second take the value 0, 1 or 2 as described previously in the Leap Second section. In the case of losing the antenna connection, the local clock (internal oscillator) is set as NTP reference, and after 55 minutes the NTP stratum level goes to 6 to inform the NTP clients the clock is in free running mode. Once the antenna connection is restored, the NTP stratum level returns to 1.

3.3 Time Settings - Configuration Summary

The table below presents all configurable time parameters and its possible values and variables.

Table 10: Summary of configurable time parameters

Timezone	h: from -12 to +14 (hours) m: 00 or 30 (minutes)
DST	selected: DST enabled unselected: DST disabled
Start/End	h: 00 up to 23 (hours) m: 00 up to 60 (minutes) first, second, third or last (week of the month) Sunday, Monday, Tuesday, Wednesday, Thursday, Friday or Saturday (day of the week) January, February, March, April, May, June, July, August, September, October, November or December (month)
NTP – Send local time	selected: the NTP/SNTP protocol will send the local time, in accordance with the timezone and DST configuration. unselected: NTP/SNTP will send the UTC time.

4 Time Signals

The Time Signals section of the Web Interface allows configuring the signals applied to the outputs of the unit. See figure below:

Time Signals

Outputs

Output	Signal	Polarity
TTL1	PPS	Normal
TTL2	PPS	Normal
OPTO1	IRIG-B	Normal
OPTO2	IRIG-B	Normal
OC1	PPS	Normal
OC2	PPS	Normal
RS232	EVENT	Normal

TMARK
00 h 00 m 00 s

DMARK
2012 December 31 00 h 00 m 00 s

PPX
4s

Pulse width
200 ms

Pulse width of 1us when unlocked
☐

Disable PPS when unlocked
☐

Cable delay compensation
0 ns

Serial Datagram

Datagram

☐ ACEB

☒ NMEA GPZDA

☐ MEINBERG

☐ Custom

\$GPZDA,%H%M%S.0,%d,%m,%Y,;%x%5%4

On-time mark
Start of first char

Serial

Speed
1200 bps

Data
7 bits

Parity
None

Stop bit
1

Figure 34: Section to configure time signals applied in the outputs

4.1 Outputs

- TTL 1 / 2: allows configuring the TTL-level electrical outputs 1 and 2. Each output has two terminals, one screw, and other BNC. Both terminals can be used simultaneously although its configuration is unique, so the same signal will be applied to both terminals;
- OPTO 1 / 2: allows configuring the two optical outputs;
- OC 1 / 2: allows configuring the two open collector outputs;
- RS232: allows configuring the Out pine signal of the serial output.

For each electrical, optical, open collector and serial output, it is possible to configure the following signals:

- OFF - Output turned off;
- PPS - Output with 1 pulse-per-second;

- 100PPS - Output with 100 pulses-per-second;
- PPX - Output with programmable frequency pulses;
- PPM - Output with 1 pulse-per-minute;
- TMARK - Output with programmable time;
- DMARK - Output with programmable date and time;
- IRIG-B - Output with IRIG-B004 signal;
- DCF77 - Output with DCF77 signal.

It is also possible to choose normal or inverted polarity for each output individually.

- The field TMARK allows configuring time to generate a pulse with daily repetition. All outputs programmed to send TMARK pulses will be programmed within the same time.
- The field DMARK allow to set a date and time for a single pulse signal. All outputs using DMARK will be programmed to this same date and time.
- The field PPX allows configuring a pulse-frequency that can vary from 1 pulse-every-2-seconds to 1 pulse-per-day. All outputs programmed to send PPX pulses will be programmed within the same pulse-frequency.
- The field Pulse Width allows the user to adjust the duty cycle (pulse width of high state) for PPS, PPM, PPX, TMARK and DMARK.
- Pulse width of 1 μ s when unlocked: When selected, this option turns the PPS, PPM, PPX, TMARK and DMARK pulses into a 1 μ s pulse when not locked to satellites, indicating that the synchronization signal is local, not global.
- Disable PPS when unlock time after (s): When selected, this option disables the PPS signal after the specified time, in seconds.
- The field Cable delay compensation allows entering a value between 0 and 999 nanoseconds (ns) to compensate propagation delay according to the cable length. Refer to Appendix D for more details of how to compensate the cable delay.

4.2 Serial datagram

- The field Datagram allows configuring a datagram sent by the serial port (TDx pin).
- ACEB, NEMEA, GPZDA, Meinberg and customizable datagrams are possible. When choosing a customizable datagram, it is necessary to enter characters with information required. For more details about ACEB, NEMEA, GPZDA and Meinberg datagrams, see Appendix C;
- A serial datagram is sent each second. The field On-time mark allows choosing if the sending will be synchronized with the beginning or the end of the datagram;
 - Start of first: pulse synchronized with the beginning of the datagram;

- Start of last: pulse synchronized with the end of the datagram;
- Serial: allows configuring the serial port parameters.
 - The field Speed allows choosing data transmission speed of the serial port, which can be 38400, 19200, 9600, 4800 or 1200 bps;
 - The field Data allows defining the data bits, which can be 7 or 8;
 - The field Parity allows choosing the serial port parity, which can be odd, even, or none;
 - The field Stop bit allows choosing the datagram stop bit, which can be 1 or 2.

4.3 Customizable datagrams

The RT430/434 allows defining a datagram "ASCII" to be sent once per second by the serial port, using the characters described below. The datagram characters can be single or special. The maximum number of character in a customizable datagram is 16.

The single characters allowed are: 0..9 A..Z a..z \$ \{ \} () [] . , ; : ! ? @ < > \$ \# * _ - \% _ \$ blank and empty.

- %H %M %S %d %m %y %x correspond to 2 characters; (Date and Time sent through datagrams refers to the local time zone configured in the RT430/434)
- %j : correspond to 3 characters (length(str) + 1 for each event);
- %Y correspond to 4 characters (length(str) + 2 for each event)
- %u %w %s %o %O %Q %1 %2 %3 %4 %5 %% : correspond to 1 character (length(str) - 1 for each event)

The following special characters can be used to enter information into the datagram:

Table 11: Customizable datagram special characters

Paramet	Values	Num. of Char.	Description
%H	00 ... 23	2	Hours
%M	00 ... 59	2	Minutes
%S	00 ... 59	2	Seconds
%j	001 ... 366	3	Day of the year
%d	01 ... 31	2	Day of the month
%m	01 ... 12	2	Month

%y	00 ... 99	2	Year (the last two digits)
%Y	2000 ... 2099	4	Year (four digits)
%u	1 ... 7	1	Day of the week (1 = Monday)
%w	0 ... 6	1	Day of the week (0 = Sunday)
%s	'S' or '_'	1	DST ('S' if DST, '_' in other case)
%o	'_' or '#'	1	Status ('_' if locked, '#' in other case)
%O	'_' or '*'	1	Status ('_' if locked, '*' in other case)
%Q	'_' or '?'	1	Status ('_' if locked, '?' in other case)
%1	<SOH>	1	Start-of-header (ASCII 01)
%2	<STX>	1	Start-of-text (ASCII 02)
%3	<ETX>	1	End-of-text (ASCII 03)
%4	<LF>	1	Line feed (ASCII 10)
%5	<CR>	1	Carriage returns (ASCII 13)
%x		2	Checksum type 1
%%	'%'	1	Character '%' (ASCII 37)

'_' is the character 'blank' (ASCII 32).

Checksum type 1 consists of two hexadecimal digits, which represent the result of a XOR from all characters comprised between '\$' and '*' ('\$' e '*' not included). It is useful for NMEA datagrams.

One example of serial datagram is presented below:

"Day:%d;Month:%m;Year:%Y;Hour:%H;Minute:%M;Second:%S;,%3"

4.4 Time Signals - Configuration Summary

The table below presents all configurable parameters for the time synchronization outputs.

Table 12: Summary of all configurable parameters for outputs

Outputs	
Output TTL 1 / 2	Signal: OFF, PPS, 100PPS, PPX, PPM, TMARK, DMARK, IRIG-B or DCF77 Polarity: normal or inverted
Output OPTO 1 / 2	Signal: OFF, PPS, 100PPS, PPX, PPM, TMARK, DMARK, IRIG-B or DCF77 Polarity: normal or inverted
Output OC 1 / 2	Signal: OFF, PPS, 100PPS, PPX, PPM, TMARK, DMARK, IRIG-B or DCF77 Polarity: normal or inverted
RS232	Signal: OFF, PPS, 100PPS, PPX, PPM, TMARK, DMARK, IRIG-B, DCF77 or EVENT Polarity: normal or inverted
TMARK	Hour: 00 up to 23 Minutes: 00 up to 59 Seconds: 00 up to 59
DMARK	Year: from 2012 to 2030 Month: January to December Day: 01 to 31 Hour: 00 up to 23 Minutes: 00 up to 59 Seconds: 00 up to 59
PPX	1 pulse-every-2-seconds to 1 pulse-per-day
Pulse width	PPS, PPM, PPX, TMARK and DMARK pulses width from 10 to 990 milliseconds
Pulse width of 1us when unlocked	selected: PPS, PPM, PPX, TMARK and DMARK pulses width of 1us when unit is unlocked unselected: pulse width does not change when unit is unlocked
Disable PPS when unlock time after (s)	selected: disable PPS signal when the unit is unlocked after defined period in seconds

	unselected: maintain PPS signal when unit is unlocked
Cable delay compensation	0 up to 999 nanoseconds
Serial datagram	
Datagram	ACEB, NEMEA, GPZDA, Meinberg or Custom
On-time-mark	Char: start of first (start of first) Char: start of last (start of last)
Serial	Speed: 38400, 19200, 9600, 4800, 2400 or 1200 bps Data: 7 or 8 Parity: none, even or odd Stop bit: 1 or 2

5 PTP Configuration

The PTP section from Web Interface allows the user to configure the parameters for the PTP protocol.

To enable the PTP in RT430/434, mark the “PTP Enabled” box. If the field “Force operation as slave” is unmarked, the RT430/434 operates as Grandmaster Clock, otherwise the unit acts as Ordinary Clock (slave). Note when equipment is operating as Ordinary, the antenna signal is ignored. To disable PTP, make sure both boxes, “PTP Enabled” and “Force operation as slave”, are disabled.

PTP

Enable PTP

☒

Profile

Custom

Domain number

3

Network protocol

UDP

Operation mode

Two step

Delay mechanism

Peer-to-Peer

Grandmaster priority

#1 128 #2 128

Force operation as

☐ Slave

Delay request interval

1 second (0)

Announce interval

1 second (0)

Sync interval

1 second (0)

Announce receipt timeout

3

Send Alternate Time TLV

☐

Send local time

☐ Enabled

Figure 35: Section to configure PTP parameters

5.1 Comparison between PTP Power Profiles

Following the latest standards, RT430/RT434 offers the most recent IEEE 1588v2 extended profiles for power system protection, control automation, and data communication applications, such as: IEEE C37.238:2017, IEC/IEEE 61850-9-3:2016 and IEEE C37.238:2011. All these are pre-configured on the RT430/RT434, making it easier to configure an IEEE 1588v2 network.

The IEEE C37.238:2017 and IEC/IEEE 61850-9-3 are completely compatible and can work together without restrictions on the same network by setting its domain number. Although the C37.238:2011 was superseded by the other two standards, it is still available for legacy networks and may be compatible depending on the IEEE 1588v2 network configuration.

The following table presents a comparison between the main characteristics of each profile.

Table 13: Comparison between PTP Power Profiles

	IEEE C37.238:2011 PTP Power Profile	IEEE C37.238:2017 PTP Power Profile	IEC 61850-9-3 PTP Profile for Power Utility Automation
Network Protocol	Ethernet Layer 2	Ethernet Layer 2	Ethernet Layer 2
Delay Mechanism	Peer-to-Peer (P2P)	Peer-to-Peer (P2P)	Peer-to-Peer (P2P)
Operation Mode	One Step	One or Two Step(s)	One or Two Step(s)
Sync / Announce Message Interval	1 per second / 1 per second	1 per second / 1 per second	1 per second / 1 per second
Grandmaster Priority	#1 and #2 = 128 Equal for all Grandmaster	Selectable, allowing to choose the best grandmaster for holdover conditions	Selectable, allowing to choose the best grandmaster for holdover conditions

5.2 PTP Profiles

When configuring PTP, the first point to be decided is which PTP profile, or which common parameters, will be used along all PTP devices. The RT430/434 has five options to be selected as profile:

- Power Profile – IEEE C37.238/2017: profile with predetermined characteristics, where the user cannot change any major parameter from PTP, such as Network Protocol, Operation mode and Delay mechanism. The characteristics are shown in next figure. The configurable parameters for Power Profile 2017 are:
 - Domain number;
 - VLAN ID and Priority;
 - Operation mode as One Step or Two Step;
 - Operation as Master or Slave;
 - Send Alternate Time TLV;
 - If the PTP should send the local time (considering the timezone and DST parameters configured) or UTC time.

The screenshot shows the PTP configuration window with the following settings:

- Enable PTP:** ☒
- Profile:** Power - IEEE C37.238/2017
- Domain number:** 0
- Network protocol:** Ethernet level 2
- VLAN:** ☒ id 0x0000 priority 4
- Operation mode:** One step
- Delay mechanism:** Peer-to-Peer
- Grandmaster priority:** #1 128 #2 128
- Force operation as:** ☐ Slave
- Delay request interval:** 1 second (0)
- Announce interval:** 1 second (0)
- Sync interval:** 1 second (0)
- Announce receipt timeout:** 3
- Send Alternate Time TLV:** ☐
- Send local time:** ☐ Enabled

Figure 36: Characteristics from Power Profile, in accordance with IEEE C37.238:2017

- Power Utility – IEC/IEEE 61850-9-3/2016: profile with predetermined characteristics, where the user cannot change any major parameter from PTP, such as Network Protocol and Delay mechanism. The characteristics are shown in next figure. The configurable parameters for Power Utility Profile are:
 - Domain number;
 - VLAN ID and Priority;
 - Operation mode as One Step or Two Step;
 - Operation as Master or Slave;
 - Send Alternate Time TLV;
 - If the PTP should send the local time (considering the timezone and DST parameters configured) or UTC time.

The screenshot shows the PTP configuration window with the following settings:

- Enable PTP:** ☒
- Profile:** Power Utility - IEC/IEEE 61850-9-3/2016
- Domain number:** 0
- Network protocol:** Ethernet level 2
- VLAN:** ☒ id 0x0005 priority 0
- Operation mode:** One step
- Delay mechanism:** Peer-to-Peer
- Grandmaster priority:** #1 128 #2 128
- Force operation as:** ☐ Slave
- Delay request interval:** 1 second (0)
- Announce interval:** 1 second (0)
- Sync interval:** 1 second (0)
- Announce receipt timeout:** 3
- Send Alternate Time TLV:** ☐
- Send local time:** ☐ Enabled

Figure 37: Characteristics from PTP for Power Utility Automation, in accordance with IEC/IEEE 61850-9-3:2016

- Power Profile – IEEE C37.238/2011: superseded by the other two standards, IEEE C37.238:2017 and IEC/IEEE 61850-9-3:2016, but it is still available for legacy networks and may be compatible depending on the IEEE 1588v2 network configuration. The characteristics are shown in next figure. The configurable parameters for Power Profile 2011 are:
 - Domain number;
 - VLAN ID and Priority;
 - Operation as Master or Slave;
 - If non-Power messages (PTP messages that are not in compliance with IEEE C37.238) should be ignored;
 - Grandmaster ID (identification);
 - Network time inaccuracy, if delays are known from the network architecture used;
 - If the PTP should send the local time (considering the timezone and DST parameters configured) or UTC time.

The screenshot shows the PTP configuration window for the Power Profile IEEE C37.238/2011. The settings are as follows:

Parameter	Value
Enable PTP	☒
Profile	Power - IEEE C37.238/2011
Domain number	0
Network protocol	Ethernet level 2
Operation mode	One step
Delay mechanism	Peer-to-Peer
Grandmaster priority	#1 128 #2 128
Force operation as	☐ Slave
Delay request interval	1 second (0)
Announce interval	1 second (0)
Sync interval	1 second (0)
Announce receipt timeout	3
Ignore non-Power Announces	☒
Send Alternate Time TLV	☒
Grandmaster id	5
Network time inaccuracy	0 ns
Send local time	☐ Enabled

Figure 38: Characteristics from PTP Power Profile IEEE C37.238:2011

- P2P Default: profile partly configurable, with some predetermined parameters, which cannot be modified. The non-editable characteristics are shown in its respective fields. The non-editable characteristics are.
 - Domain number 0.
 - Priority 128 in both Ethernet ports.
 - Operation as master only.
- Custom Profile: profile with all features freely configurable by a user.

5.3 Domain number

The RT430/434 allows configuring the domain number to be identified by the PTP clock, so it only answers messages from this domain. The domain

number field allows selecting a domain number between 0 and 255 which the unit will recognize.

5.4 Network protocol

This field defines the network layers where the PTP protocol will be applied. It is possible to use PTP protocol in a network layer with IEEE 802.3 Ethernet (layer 2) or UDP/IPv4 (layer 3) connection. If Ethernet (layer 2) is selected, VLAN may be used.

5.5 Operation mode

The field operation mode allows configuring the operation mode according to the form RT430/434 sends its messages, as follows:

- One-step: Sync information and timestamp information are sent in the same data packet;
- Two-step: Sync information is sent in one data packet, and timestamp information is sent in another data packet.

5.6 Delay mechanism

The RT430/434 is capable of measuring the delay between master and slave clocks using End-to-end and Peer-to-peer, according to IEEE1588 standard. The field Delay mechanism allows configuring the type of measurement of the delay, as follow:

- End-to-end: measurement of delay across the network between master clock and slave clock;
- Peer-to-peer: measurement of delay between all PTP-aware devices, including switches when operating as transparent or boundary clock.

5.7 Grandmaster Priority

When configured as master, BMC algorithm tie breaking criteria priorities must be attributed. The fields Grandmaster priority #1 and #2 allow configuring the priorities of both Ethernet ports, in which #1 is the first and #2 is the last tie breaking criterion. Between the first and the last tie breaking criterion, other clock characteristics are analyzed. The priority values can vary from 0 to 255. The lower the attributed value is, the higher its priority is.

5.8 PTP Messages

In PTP protocol, messages containing Sync information and timestamps are sent across the network in multicast mode.

Announce messages are used to inform devices connected to the network about the existence of a master clock available to send Sync packets. The

clock connected to the network operating as a master should send Sync messages. In case it is a two-step clock, Follow Up messages containing the timestamp will be send after the Sync messages.

In RT430/434, it is possible to choose the frequency to send messages and the waiting time of Announce message receipt, through the fields below:

- Delay request interval allows choosing the frequency to send messages with delay measurement. It is possible to configure the unit to send 16 messages per second until one message every-32-seconds.
- Announce interval allows choosing the frequency to send messages that apply the device to become a network master candidate. It is possible to configure the unit to send 16 messages per second until one message every-32-seconds.
- Sync interval allows choosing the frequency to send Sync messages. It is possible to configure the unit to send 16 messages per second until one message every-32-seconds.
- Announce receipt timeout allows choosing the waiting time of Announce message receipt when RT430/434 is being used as slave. In case an Announce message is not received within this time interval, the unit assumes that the current master clock is unavailable and executes the BMC to select another master clock. It is possible to configure values between 2 and 255 seconds.

5.9 PTP - Configuration Summary

The table below presents all configurable PTP parameters and its possible values and variables.

Table 14: Summary of configurable PTP parameters

Profile	
Power IEEE C37.238	Predetermined parameters
Power Utility IEC 61850-9-3	Predetermined parameters
P2P Default	Domain number 0, priority 128, and operation as master
Custom	All parameters are configurable
Parameters	
Domain number	From 0 to 255
Network protocol	UDP or Ethernet level 2
Operation mode	one-step or two-step

Delay	P2P or E2E
Grandmaster Priority	# 1 from 0 to 255 # 2 from 0 to 255
For operation as	Slave: enables the use as slave
Intervals between sent messages	
Delay request	From 1/16 to 32 seconds
Announce	From 1/16 to 32 seconds
Sync	From 1/16 to 32 seconds
Response time of messages	
Announce receipt	From 2 to 255 seconds
TLV Messages	
Send Alternate Time TLV	Selected: TLV messages will be sent Unselected: TLV messages will not be sent
UTC or Local Time	
Send local time	Selected: local time is sent through PTP protocol. Unselected: UTC is sent through PTP protocol.

6 Setup

The Setup section of the Web Interface allows updating the firmware, manipulating configurations, changing key and configuring password. Firmware and key change (equipment upgrade) instructions are described in Maintenance chapter.

Firmware Update

File No file chosen

Configuration Management

Backup configuration

Click the button below to download the configuration file.

Restore configuration

File No file chosen

Restore to factory default configuration

Click the button below to overwrite all configuration to factory default settings. Save a **Backup configuration** before proceed with this option. The system will be automatically rebooted after the restore.

Equipment Key

Key

Password configuration

New password

Confirm password

GPS configuration

☐ Enable GPS almanac reset on equipment power up.

☐ Enable GPS Stationary mode.

Demo Mode

☐ Enable demo mode - force equipment to LOCKED, using internal clock as reference.

System log file

Click the button below to download the system log.

Reboot System

Click the button below to reboot the system.

Generate HTTPS Certificate

Click the button below to generate HTTPS certificate.

Figure 39: Setup section in Web Interface

6.1 Configuration Management

- **Backup Configuration:** It is possible to receive a file with the current configuration of the unit and store it in a directory on the computer. Saving the final configuration of the unit as a backup is recommended.
 - **Download:** allows saving the current configuration of the unit in “.rt430” or “.rt434”, respectively to RT430 and RT434. By clicking <Download> a window will open to save the file in a directory on the computer.
- **Restore Configuration:** It is possible to send a configuration file in “.rt430” or “.rt434” format to the respectively unit.
 - **File:** allows entering the directory and file name of the configuration that will be sent to the unit.
 - **Search:** allows searching the configuration file in Windows' directories.
 - **Restore:** allows transmitting the selected configuration file to the unit. By clicking <Restore> a window will open requiring configuration username and password. Enter the username and password and click <Login>. To cancel the action, click <Cancel>. During the transmission, the unit will go momentarily out of operation.
- **Restore to factory default configuration:** Restore the equipment to factory default settings.

6.2 Password configuration

- **New password:** allows entering a new password for configuration.
- **Confirm password:** confirmation of the new password entered.

6.3 Reset Satellites Almanac

This option deletes the satellites Almanac data stored in the clock. Afterwards the equipment will take several minutes to rebuild the Almanac. The almanac consists of orbit courses and status information for each satellite in the constellation, an ionosphere model, and information to relate satellites derived time to Coordinated Universal Time (UTC).

6.4 Stationary Mode

This option enable the Stationary Mode, which keeps the equipment in locked state even with one satellite. Note the equipment must track at least four satellites before entering in stationary mode. Besides, if this option is enabled, the equipment must be in a fixed position. To enable the Stationary Mode, select the option “Enabled Stationary Mode” and click on the <Apply> button.

6.5 Demo mode

Mostly used in demonstrations, this option forces the clock into a LOCKED state independently if the antenna is or is not connected, as the internal oscillator is used as time reference. In demo mode, the Locked Led will remain alight and the dry contact relay opened. When the Demo Mode is activated, it is possible to configure the date and time manually, in Time Settings tab from equipment Web Interface.

All time protocols work in Demo Mode: PTP, NTP, SNTP, IRIG-B and all other low frequency signals.

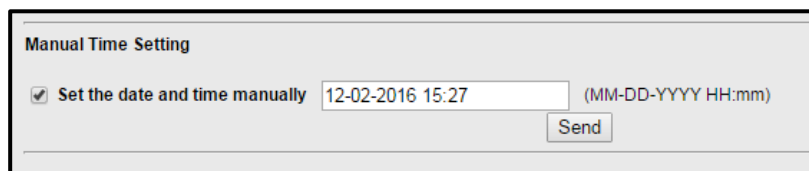


Figure 40: Manual Time setting – only available in Demo Mode

Note: in demo mode the Ethernet ports are not in sync with each other, although they follow the manual date and time settings. This means that PTP slaves connected to different Ethernet ports will have different time stamp and consequently might not be synced. The physical interfaces (BNC, optical, open collector...) are always in sync with the Ethernet port 1.

6.6 Log Files

Technical support may request log files in case maintenance is required.

6.7 Reboot System

This feature reboots the system without the need to withdraw the power supply.

6.8 Generate HTTPS Certificate

A default HTTPS certificate is generated upon first boot. The created certificate is valid for 10 years and it is self-signed (each device will have its own individual key). The user may renew the certificate by clicking in the button "Generate HTTP Certificate", and the new created certificate will also be valid for 10 years.

In case the HTTPS certificate expires, the user may use a HTTP connection to access the web interface and generate a new HTTPS certificate.

Alternatively, if the allowed by the HTML browser, the user may create an exception to login through HTTPS mode (even considering the expired certificate) and generate a new HTTPS certificate.

Note a new certificate will only be created if the user clicks on this button. Equipment rebooting or firmware upgrade will not renew the HTTPS certificate.

7 Cyber Security Notice

Once RT43x has been properly configured, GE suggests blocking the TCP/IP Port 80 and 443 in the Ethernet switch port interface the clock is connected to during clock run-time operation, thus impeding RT43x remote access via web browser. Whenever intending to access RT43x web interface, the TCP/IP Port configuration in the Ethernet switch must be reversed.

GE recommends RT43x monitoring purposed via SNMP to be kept at Local Area Network (LAN) only, disabling remote access to RT43x UDP 161 Port.

Reason RT430/RT434

GNSS Precision-Time Clock

Chapter 7: Maintenance

This chapter describes the information to consider for an eventual maintenance.

For any further assistance required please contact the information and call center as follows:

GE Vernova:

Worldwide Contact Center

Web: <https://www.gevernova.com/grid-solutions/contact>

Phone: +44 (0) 1785 250 070

1 Time Synchronization Failure (Locked Signaling)

The clock availability is higher than 99.999%, but time synchronization failure may occur and the locked relay will alarm when it does. If availability rate is lower than that, the follow actions are recommended:

- Check for configuration being transmitted to the unit. During transmission, the unit should momentarily go out of operation to reboot. This behavior is normal and no action is required. The Locked indicator will lit as soon as the unit resumes operation.
- Make sure the GNSS antenna is properly connected to the unit.
- Make sure the antenna cable being used is in accordance with the specifications presented in Technical Specification.
- Make sure the unit is synchronized with at least 4 satellites by checking the Web Interface. Otherwise, check the location of the antenna, making sure that it is installed according to the recommendations of Installation chapter.

If the unit is operating without time reference in the GNSS antenna, the failure may be signaled in different ways: Local interface, Web Interface, signaling relay, and data packets from IRIG-B, NTP, PTP and SNMP protocols.

1.1 Locked indicator (HMI)

The Locked indicator located in the front panel will be off when there is no time reference in the GNSS antenna input. As soon as a GNSS antenna is connected, the indicator will start blinking while it downloads a satellite

almanac. This behavior is normal and no actions are necessary. The Locked indicator will stop blinking and stay lit as soon as the download is completed (it may take a few minutes when a unit is moved over long distances or has been out of operation for a long period).

1.2 Remote monitoring (Web Interface)

In the monitoring area of the Web Interface it is shown the information Locked and the number of satellites when there is time reference in the GNSS antenna input, and Unlocked when reference is disconnected.

1.3 Dry-contact relay (Locked)

The RT430/434 has a dry-contact normally closed for remotely signaling the locked state of the unit. As the unit is powered up, the dry-contact Locked is normally closed. The dry-contact relay operates along with the Locked indicator, and while RT430/434 is locked, the dry-contact relay is open. Thus, in case the unit loses satellite reference, the dry-contact closes signaling the problem.

1.4 IRIG-B Signal

When the Time Quality bits from IRIG-B signal are all in 0, the unit is in Locked state, i.e., there is time reference in the GNSS antenna input. In case the reference is disconnected or the signal is weak, the bits combination will differ from zero.

1.5 PTP Protocol

In PTP protocol, there is a bit called time traceable that, when set, informs the existence of time reference in the GNSS antenna input. Besides the existence of a reference signal, it is possible to qualify the signal, according to the bits clock class and clock accuracy, in which the criterion for assessing the quality of the signal is configured in the device that receives the PTP messages.

1.6 NTP Protocol

In NTP protocol, information is given in layers, known as Stratum, numbered from 0 to 16. Layer 1 indicates the unit is operating with time reference from the GNSS antenna input, when the antenna is connected. Stratum layer 6 indicates the reference was interrupted, i.e., the unit lost the antenna connection. A stratum level 16 means an antenna was never connected to the unit after initialization.

1.7 SNTP Protocol

In SNTP protocol, a data set is sent containing time synchronization and the status of the external time reference.

When the status data is zero, it represents the lack of time reference in the GNSS antenna input. When it is 1, it represents the existence of reference in the GNSS antenna input, i.e., it is in LOCKED state.

2 Firmware Update

Eventually, new firmware versions will be released with updates and improvements to the unit.

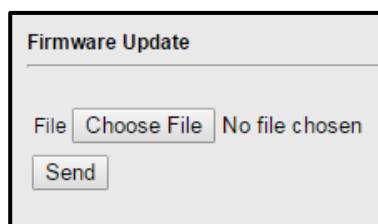


Figure 41: Section to update firmware

To update the unit firmware, access the Setup section of the Web Interface by typing the unit IP address in a default browser and follow the steps below:

1. Click <SEARCH> and it will allow the search of a new firmware update file in the directories. Enter the directory and the firmware update file name in the <FILE> field and it will be sent to the unit. The update file has the extension ".fw430" for RT430 and ".fw434" for RT434.
2. Click < SEND> to send the new firmware to the unit.
3. After clicking <SEND>, a new window will open requesting username and configuration password. Enter username and password and click <LOGIN>. To cancel the action, click on <CANCEL>.
4. During the transmission, the unit will momentarily go out of operation.
5. After the change is completed, check the main page of the Web Interface.

Note: After updating, it is recommended to clear the browsing data (CTRL+ F5) when accessing the web interface for the first time.

3 Equipment Upgrade - Key Change

It is possible to update the unit key in order to enable new features, according to the commercial policy. Contact sales to acquire a new key to enable the desired features.

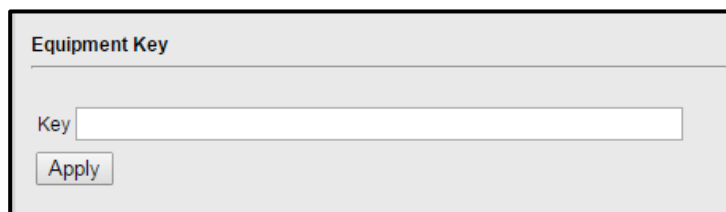
A screenshot of a web interface titled "Equipment Key". It features a text input field labeled "Key" and a button labeled "Apply". The interface is simple with a light gray background and a thin border.

Figure 42: Section to equipment upgrade – key change

To change the unit key, access the Setup section from Web Interface, typing the unit IP address in a default browser and follow the steps below:

1. Enter the new key (36 alphanumeric characters) in the Key field.
2. Click <Apply> to send the new key to the unit.
3. After clicking <Apply>, a new window will open requesting username and configuration password. Enter username and password and click <Login>.

Note: If the key mismatches the MAC Addresses from the equipment, a warning message will pop up saying “The new Key’s MAC does not match with the current Key”. In this case, it is recommended to cancel the upgrade and contact the local support. If the user decides to continue, the new key will change the equipment MAC addresses.

4. During the transmission, the unit will momentarily go out of operation. A message communicating the key change will show up on the screen.
5. After the change is completed, check the main page of the Web Interface.

4 Cleaning Instructions

Before cleaning the equipment, make sure that the primary voltage is removed. If it is necessary cleaning the exterior of the equipment, use only a dry cloth. Internally it is not required any cleaning.

5 Equipment Return

All parts and components comprising Reason devices must be repaired exclusively by GE Vernova. In case of equipment malfunction, the customer must get in contact with GE Vernova’s Contact Centre and never attempt to repair the device by his own.

To request equipment repair service, call GE Vernova to check out shipment options and receive the technical assistance order code. The equipment must be packed in its original package or a suitable package to protect against impacts and moisture.

Send equipment to address supplied including the sender’s identification and the technical assistance reference.

Reason RT430/RT434

GNSS Precision-Time Clock

Chapter 8: Technical Specification

This chapter describes the technical specifications of the product. The information described in this chapter goes for RT430 and RT434, unless specified.

1 Power Supply

Table 15: Power supply specifications

Number of Power Supply	Up to 2 power supplies	
Operating nominal voltage	100-250Vdc, 110-240Vac	24/48Vdc
Operating voltage range	80-300Vdc, 88-264Vac	18-75Vdc
Frequency	50/60 Hz ± 3 Hz	N/A
Power Consumption	MAX 20 VA	MAX 10 W
	Typical 15 W	Typical 8 W

2 GNSS Antenna

2.1 GNSS Antenna Receiver

Table 16: GNSS Antenna input specifications for temporal synchronization

GNSS Receiver	GPS + GLONASS L1 Frequency concurrently
Sensibility	-165 dBm (Tracking & Navigation)
	-160 dBm (Reacquisition)
	-148 dBm (Cold Start)
Antenna type	Active

Antenna's supply	3.3 V, max 100 mA
Connector	BNC (female)
Time Receiver Autonomous Integrity Monitoring (TRAIM) supported	

2.2 GNSS Antenna Type

Table 17: GNSS Antenna specifications

Type	3.3 V Active GNSS antenna (<20 mA)
Frequency	1588 ± 3MHz
Output / VSWR	2.0 Max
Impedance	50 Ω
Gain	30dB @ 25°C
Noise	3.3dB max (25°C ± 5°C)
Azimuth coverage	360° (omni-directional)
Elevation coverage	0°-90° elevation (hemispherical)
Operating Temperature	-40°C to +90°C
Connector	TNC Female

2.3 Antenna Cable

Table 18: Antenna Cable specifications

Length	Delay (ns)	Description	Attenuation @1500MHz
25 m (82 ft)	102,6	TNC Male to BNC Male connectors, RG58 Type	< 0.5 dB/m

40 m (131 ft)	163,6	TNC Male to BNC Male connectors, RG58 Type	< 0.5 dB/m
100 m (328 ft)	407,5	TNC Male to BNC Male connectors, RG8 Type	< 0.2 dB/m
Velocity of propagation		82%	
Impedance		50 ohms	
Capacitance		81pF/m	

2.4 Surge Arrester

Table 19: Surge arrester specifications

Nominal discharge current I_n (8/20 μ s)	10 kA
Dynamic residual voltage	< 600 V
Band width	< 4 GHz
Insertion Loss	$\leq$ 0.1dB
Impedance	50 Ω
Connector	BNC
Includes 1 meter long cable	

3 Internal Oscillator

Table 20: Internal oscillator specifications

Internal Oscillator Type	TCXO
Short Term Stability	5 ns / s
Time Pulse Accuracy ¹	$\leq$ 50 ns
Drift, One day	$\pm$ 800 μ s (typical ²)

	< 100 ppb (max)
Accuracy GNSS Synchronous, Average 24h	5 ppb
Super Capacitor Autonomy ³	80 hours

¹ RT430/434 output signal. GNSS PPS Accuracy is ≤ 20 ns

² Typical drift was measured indoors in laboratory

³ Super capacitor supplies energy to keep internal time after power supply outage.

4 Outputs

4.1 Connectors

See figures below to refer to the rear panel connectors of RT430/434.

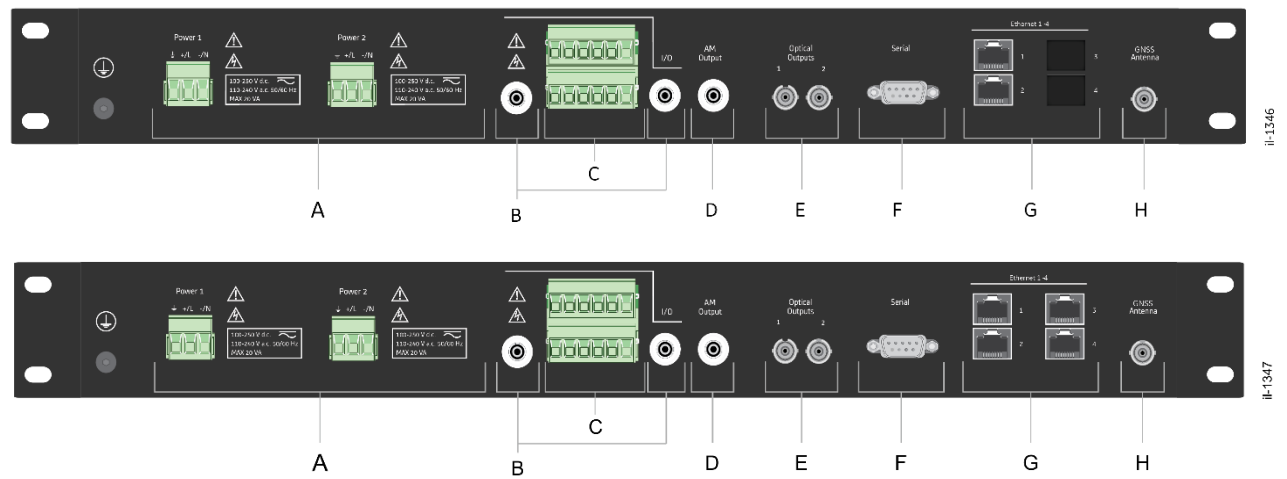


Figure 43: Rear panel connectors of RT430 (top) and RT434 (bottom)

Table 21: RT430/434 rear panel connectors

Indicator	Description
A	2 power supplies (one is optional), AC/DC high voltage or DC low voltage
B	2 TTL electrical outputs using BNC connectors, one of them insulated
C	2 TTL electrical outputs using Euro Type connectors, one of them insulated; 2 open collector outputs; Dry-Contact relay (Locked);

	And 1 CMOS/TTL level event input
D	1 modulated-amplitude output for IRIG-B124 signal
E	2 optical outputs using ST connector
F	RS232 and RS422/485 serial port
G	2 RJ45 communication ports via Ethernet network (RT430) 4 RJ45 communication ports via Ethernet network (RT434)
H	GNSS antenna input

4.2 TTL Electrical Outputs

Table 22: Electrical outputs specifications

Time Accuracy	50 ns (mean) 100 ns (peak)
Number of Outputs	4
TTL Voltage Level	5 Vdc
High Level	> 4.8 Vdc
Low Level	< 0.2 Vdc
Impedance	18 Ω
Maximum current	150 mA
Connectors	2x 2-pin Euro Type 2x BNC
Two electrical outputs are insulated, one from 2-pin connector and another from BNC connector.	

4.3 Open Collector Electrical Outputs

Table 23: Open collector outputs specifications

Number of Outputs	2
Maximum collector emitter DC voltage	400 Vdc
Maximum current	300 mA
Connectors	2-pin Euro Type

4.4 Optical Outputs

Table 24: Optical outputs specifications

Time Accuracy	50 ns (mean) 100 ns (peak)
Number of Outputs	2
Connector	ST
Wavelength	820 nm
Fiber Type	Multimode 50/125 μm , 62.5/125 μm , 100/140 μm or 200 μm HCS
Emission power	- 17.8 dBm (50 / 125 μm) - 14.0 dBm (62,5 / 125 μm) - 8.5 dBm (100 / 140 μm) - 5.7 dBm (200 μm HCS)

4.5 Amplitude Modulated Output

Table 25: Amplitude modulated output

Number of Outputs	1
Signal	IRIG-B124

Connector	BNC (female)
Empty Amplitude	4 Vpp
50 Ω Amplitude	3 Vpp
Relative level High/Low	3.3
Carrier Frequency	1 kHz
Outputs Impedance	15 Ω
Maximum Current	80 mA

4.6 Serial Port (RS232, RS422/485)

Table 26: RS232 or RS422/485 serial port specifications

Number of Ports	1
Signal Level	RS232 or RS422/485
Bitrate	1200, 2400, 4800, 9600, 19200 or 38400 bps
Data bits	7 or 8
Stop bits	1 or 2
Parity	none, even or odd
Connector	DB9 (female), standard DTE

5 Dry-contact Relay

Table 27: Dry-contact relay specification

Number of Relays	1
Max AC Voltage and Current Capacity	250 Vac / 500 mA
Max DC Current Capacity	500 mA @ 24 Vdc 500 mA @ 48 Vdc

	400 mA @ 125 Vdc 150mA @ 250 Vdc (max voltage)
Contact	Normally Closed

6 Event Input

Table 28: Event Input specification

Number of Inputs	1
TTL Voltage Level	5 Vdc
Signals	PPS, PPM or any other pulse with frequency lower than 100Hz

7 Precision Time Protocol PTP (IEEE 1588)

Table 29: PTP time synchronization protocol specifications

Time Accuracy	< 100 ns
Protocols	UDP/IPv4 (Layer 3) IEEE 802.3 (Layer 2)
Delay Compensation	End-to-End (E2E) Peer-to-Peer (P2P)
Profiles	- Power - IEEE C37.238/2011 - Power - IEEE C37.238/2017 - Power Utility - IEC/IEEE 61850-9-3/2016 - P2P Default - Custom

8 Ethernet Ports

Table 30: Ethernet ports specification

Number of ports	RT430 has 2 independent Ethernet ports RT434 has 4 independent Ethernet ports
Transmission Rates	10/100 Mbps
Connector	RJ45
Protocols Supported	NTP v2 (RFC 1119) NTP v3 (RFC 1305) NTP v4 (RFC 5905) SNTP (RFC 1769/2030/4330) SNMP (v1, v2c) including MIB support. IEEE 1588 PTP IEC 62439-3 PRP (RT430 only) HTTP, TCP/IP, UDP

9 Environment

Table 31: Environment specification

Operating temperature range	-40°C ... +55°C (or -40°F to +131°F)
As tested per IEC 60068-2-1	-40°C
As tested per IEC 60068-2-2	+85°C
Maximum operating altitude	2000 m (6560 ft)
Relative humidity	5 ... 95%, non-condensing

Table 32: Enclosure Protection IEC 60529

Front flush mounted with panel	IP40
Rear and sides	IP20
Product safety protection	IP20 (due to live connection on the terminal block)

10 Type Tests

Table 33: EMC tests were performed according to IEC 60255-26 referring to the following standards

IEC 61000-4-2:2008	6 kV contact / 8 kV air
IEC 61000-4-3:2006	10 V/m
IEC 61000-4-4:2012	2 kV @ 5 kHz
IEC 61000-4-5:2005	Differential mode: 1 kV Common mode: 2 kV
IEC 61000-4-6:2008	10 V
IEC 61000-4-8:2009	30 A/m continuous 300 A/m @ 1 s
IEC 61000-4-11:2004 IEC 61000-4-29:2000	- A.C. and D.C. voltage dips Test level: 0% residual voltage Duration time A.C.: 1 cycle D.C.: 16,6 ms - Test level: 40% residual voltage Duration time A.C.: 12 cycles D.C.: 200ms - Test level: 70% residual voltage Duration time A.C.: 30 cycles D.C.: 500 ms - A.C. and D.C. voltage interruptions Test level: 0% residual voltage Duration time A.C.: 300 cycles

	D.C.: 5 s
IEC 61000-4-17:1999	Test level: 15% of rated DC value Test frequency: 120 Hz, sinusoidal waveform
IEC 61000-4-18:2006	Voltage oscillation frequency: 1 MHz Differential mode: 1 kV peak voltage; Common mode: 2.5 kV peak voltage
IEC 60255-26:2008	Shut-down ramp: 60 s Power off: 5 m Start-up ramp: 60 s
CISPR11:2009	Radiated emission 30 to 230 MHz – 50 dB ($\mu\text{V}/\text{m}$) quasi peak at 3 m and 230 to 1000 MHz – 57 dB ($\mu\text{V}/\text{m}$) quasi peak at 3 m
CISPR22:2008	Radiated emission The definition of the limit frequency is based on the maximum internal frequency of the equipment. On RT430/434, the maximum internal frequency is 100 MHz. For this case, the levels of CISPR 11 satisfy the normative IEC 60255-26. Conducted emission 0.15 to 0.50 MHz – 79dB (μV) quasi peak; 66 dB (μV) average 0.5 to 30 MHz – 73dB (μV) quasi peak; 60 dB (μV) average

Table 34: Safety tests

IEC 61010-1 CE Certification	Safety Requirements
IEC 60255-5	Impulse: 5 kV Dielectric withstand: 3.3 kVdc Insulation: > 100 M Ω

Table 35: Environmental tests

IEC 60068-2-1	-40°C, 16 hours (Cold)
IEC 60068-2-2	+85°C, 16 hours (Dry heat)
IEC 60068-2-30	95% no condensation, +55°C (Damp heat)
IEC 60068-2-14	-40°C to +85°C / 9 hours / 2 cycles (Change of temperature)
IEC 60255-21-1	Class 1 (Vibration)
IEC 60255-21-2	Class 1 (Shock)
IEC 60255-21-3	Class 2 (Seismic)

11 Dimensions, Weight

Table 36: Dimensions and weight specification RT430/434

Height	44.45 mm (1 U; 1.75 in)
Width (body)	430 mm (16.9 in)
Depth	180 mm (7.1 in)
Weight	2.7 kg (5.9 lbs)

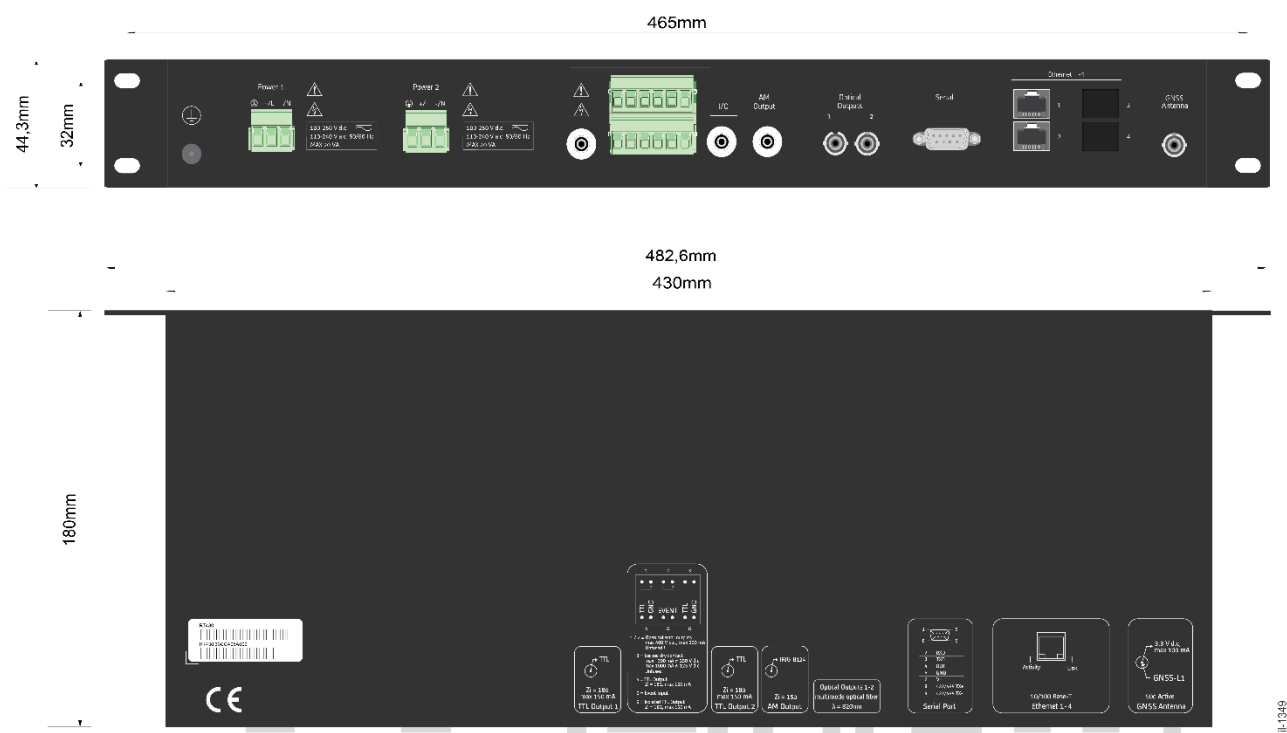


Figure 44: RT430/434 Dimensions

Reason RT430/RT434

GNSS Precision-Time Clock

Chapter 9: Ordering Options

This chapter describes the CORTEC number formation from RT430 and RT434.

1 RT430 GNSS Cortec

Variants	IED Order Number															Optional		
	1-5	6	7	8	9	10	11	12	13-14	15	16	17	18					
Model Type RT430 GNSS Precision-Time Clock	RT430																	
Power Supply 1 24-48 Vdc 100-250 Vdc / 110-240 Vac		1 3																
Power Supply 2 24-48 Vdc 100-250 Vdc / 110-240 Vac Not installed			1 3 X															
Ethernet Interface 1 RJ45 copper 100BASE-TX for configuration only RJ45 copper 100BASE-TX for NTP server and configuration RJ45 copper 100BASE-TX for PTP (IEEE 1588) server, NTP server and configuration				C N P														
Ethernet Interface 2 RJ45 copper 100BASE-TX for configuration only RJ45 copper 100BASE-TX for NTP server and configuration * RJ45 copper 100BASE-TX for PTP (IEEE 1588) server, NTP server and configuration ** PRP-redundant RJ45 copper 100BASE-TX port (same function as interface 1) *					C N P R													
Satellite constellations supported GPS GPS and GLONASS						A B												
Oscillator Type TCXO								2										
Customization / Regionalisation GE branding									C									
Firmware Version Latest available firmware - 08 Firmware version number - 07 (withdraw)										08 07								
Hardware Design Suffix GNSS version											B							
GPS Antenna Without antenna 3.3V TNC Female active GNSS antenna													0 2					
Antenna Cable No cable 25 m (82 ft) TNC Male to BNC Male (Attenuation < 0.5 dB/m @ 1500 MHZ) 40 m (131 ft) TNC Male to BNC Male (Attenuation < 0.5 dB/m @ 1500 MHZ) 100 m (328 ft) TNC Male to BNC Male (Attenuation < 0.2 dB/m @ 1500 MHZ)													0 2 3 5					
Surge Arrester Without surge arrester 10 kA, 50 Ohms, BNC-type connector Surge Arrester for 0-2000 MHz														0 1				

* Option only available if "N" or "P" selected in Ethernet Interface 1

** Option only available if "P" selected in Ethernet Interface 1

Issue K

2 RT434 GNSS Cortec

Variants	IED Order Number															Optional		
	1-5	6	7	8	9	10	11	12	13-14	15	16	17	18					
Model Type RT434 GNSS Precision-Time Clock	RT434																	
Power Supply 1 24-48 Vdc 100-250 Vdc / 110-240 Vac		1 3																
Power Supply 2 24-48 Vdc 100-250 Vdc / 110-240 Vac Not installed			1 3 X															
Ethernet Interface 1 and 2 RJ45 copper 100BASE-TX for configuration only RJ45 copper 100BASE-TX for NTP server and configuration RJ45 copper 100BASE-TX for PTP (IEEE 1588) server, NTP server and configuration				C N P														
Ethernet Interface 3 and 4 RJ45 copper 100BASE-TX for configuration only RJ45 copper 100BASE-TX for NTP server and configuration * RJ45 copper 100BASE-TX for PTP (IEEE 1588) server, NTP server and configuration **					C N P													
Satellite constellations supported GPS GPS and GLONASS						A B												
Oscillator Type TCXO							2											
Customization / Regionalisation GE branding								C										
Firmware Version Latest available firmware - 08 Firmware version number - 07 (withdraw)									08 07									
Hardware Design Suffix GNSS version										B								
GPS Antenna Without antenna 3.3V TNC Female active GNSS antenna											0 2							
Antenna Cable No cable 25 m (82 ft) TNC Male to BNC Male (Attenuation < 0.5 dB/m @ 1500 MHZ) 40 m (131 ft) TNC Male to BNC Male (Attenuation < 0.5 dB/m @ 1500 MHZ) 100 m (328 ft) TNC Male to BNC Male (Attenuation < 0.2 dB/m @ 1500 MHZ)											0 2 3 5							
Surge Arrester Without surge arrester 10 kA, 50 Ohms, BNC-type connector Surge Arrester for 0-2000 MHz											0 1							

* Option only available if "N" or "P" selected in Ethernet Interface 1 and 2

** Option only available if "P" selected in Ethernet Interface 1 and 2

Issue K

Reason RT430/RT434

GNSS Precision-Time Clock

Chapter 10: Appendixes

Appendix A – IRIG-B Standard Summary

Table 37: IRIG-B standard summary

0	P_r	reference bit (P_r)	
1	$P_r + 10\text{ ms}$	seconds 1	seconds (0 ... 59 or 60)
2	$P_r + 20\text{ ms}$	seconds 2	
3	$P_r + 30\text{ ms}$	seconds 4	
4	$P_r + 40\text{ ms}$	seconds 8	
5	$P_r + 50\text{ ms}$	index bit (0)	
6	$P_r + 60\text{ ms}$	seconds 10	
7	$P_r + 70\text{ ms}$	seconds 20	
8	$P_r + 80\text{ ms}$	seconds 40	
9	$P_r + 90\text{ ms}$	position identifier 1 (P_1)	
10	$P_r + 100\text{ ms}$	minutes 1	minutes (0 ... 59)
11	$P_r + 110\text{ ms}$	minutes 2	
12	$P_r + 120\text{ ms}$	minutes 4	
13	$P_r + 130\text{ ms}$	minutes 8	
14	$P_r + 140\text{ ms}$	index bit (0)	

15	$P_r + 150 \text{ ms}$	minutes 10	
16	$P_r + 160 \text{ ms}$	minutes 20	
17	$P_r + 170 \text{ ms}$	minutes 40	
18	$P_r + 180 \text{ ms}$	index bit (0)	
19	$P_r + 190 \text{ ms}$	position identifier 2 (P_2)	
20	$P_r + 200 \text{ ms}$	hours 1	hours (0 ... 23)
21	$P_r + 210 \text{ ms}$	hours 2	
22	$P_r + 220 \text{ ms}$	hours 4	
23	$P_r + 230 \text{ ms}$	hours 8	
24	$P_r + 240 \text{ ms}$	index bit (0)	
25	$P_r + 250 \text{ ms}$	hours 10	
26	$P_r + 260 \text{ ms}$	hours 20	
27	$P_r + 270 \text{ ms}$	index bit (0)	
28	$P_r + 280 \text{ ms}$	index bit (0)	
29	$P_r + 290 \text{ ms}$	position identifier 3 (P_3)	
30	$P_r + 300 \text{ ms}$	days 1	day of the year (1 ... 365 or 366)
31	$P_r + 310 \text{ ms}$	days 2	
32	$P_r + 320 \text{ ms}$	days 4	
33	$P_r + 330 \text{ ms}$	days 8	
34	$P_r + 340 \text{ ms}$	index bit (0)	
35	$P_r + 350 \text{ ms}$	days 10	
36	$P_r + 360 \text{ ms}$	days 20	
37	$P_r + 370 \text{ ms}$	days 40	

38	$P_r + 380 \text{ ms}$	days 80	
39	$P_r + 390 \text{ ms}$	position identifier 4 (P_4)	
40	$P_r + 400 \text{ ms}$	days 100	
41	$P_r + 410 \text{ ms}$	days 200	
42	$P_r + 420 \text{ ms}$	index bit (0)	
43	$P_r + 430 \text{ ms}$	index bit (0)	
44	$P_r + 440 \text{ ms}$	index bit (0)	
45	$P_r + 450 \text{ ms}$	index bit (0)	
46	$P_r + 460 \text{ ms}$	index bit (0)	
47	$P_r + 470 \text{ ms}$	index bit (0)	
48	$P_r + 480 \text{ ms}$	index bit (0)	
49	$P_r + 490 \text{ ms}$	position identifier 5 (P_5)	
50	$P_r + 500 \text{ ms}$	year 1	The last 2 digits of the year (00 ... 99)
51	$P_r + 510 \text{ ms}$	year 2	
52	$P_r + 520 \text{ ms}$	year 4	
53	$P_r + 530 \text{ ms}$	year 8	
54	$P_r + 540 \text{ ms}$	index bit (0)	
55	$P_r + 550 \text{ ms}$	year 10	
56	$P_r + 560 \text{ ms}$	year 20	
57	$P_r + 570 \text{ ms}$	year 40	
58	$P_r + 580 \text{ ms}$	year 80	
59	$P_r + 590 \text{ ms}$	position identifier 6 (P_6)	
60	$P_r + 600 \text{ ms}$	index bit (0)	

61	$P_r + 610$ ms	index bit (0)	
62	$P_r + 620$ ms	Daylight Saving Pending (DSP)	1 during the minute before beginning or end of DST
63	$P_r + 630$ ms	Daylight Saving Time (DST)	1 during DST
64	$P_r + 640$ ms	Time Offset Sign (0=+, 1=-)	difference between local time and UTC (negative for West Greenwich)
65	$P_r + 650$ ms	Time Offset 1	difference between local time and UTC (-12 ... +12)
66	$P_r + 660$ ms	Time Offset 2	
67	$P_r + 670$ ms	Time Offset 4	
68	$P_r + 680$ ms	Time Offset 8	
69	$P_r + 690$ ms	position identifier 7 (P_7)	
70	$P_r + 700$ ms	Time Offset – 0.5h	0 – none 1 – Additional 0.5h time offset
71	$P_r + 710$ ms	Time Quality (bit 1)	4-bit code representing approx. clock time error: 0000: Clock is locked 0001, 0010, ..., 1010, 1011: Time within 10^{-9} s, 10^{-8} s, ..., 1s, 10s of UTC 1111: Fault – time not reliable
72	$P_r + 720$ ms	Time Quality (bit 2)	
73	$P_r + 730$ ms	Time Quality (bit 3)	
74	$P_r + 740$ ms	Time Quality (bit 4)	
75	$P_r + 750$ ms	Parity (odd)	Module 2 of the sum of the data bits 0 to 74 (Bits 75-99 not included in the sum)
76	$P_r + 760$ ms	Continuous Time Quality (bit 1)	3-bit code representing the estimated maximum time error in the transmitted message.
77	$P_r + 770$ ms	Continuous Time Quality (bit 2)	
78	$P_r + 780$ ms	Continuous Time Quality (bit 3)	
79	$P_r + 790$ ms	position identifier 8 (P_8)	
80	$P_r + 800$ ms	time-of-day 1	seconds of the year

81	$P_r + 810 \text{ ms}$	time-of-day 2	(0 ... 86399)
82	$P_r + 820 \text{ ms}$	time-of-day 4	
83	$P_r + 830 \text{ ms}$	time-of-day 8	
84	$P_r + 840 \text{ ms}$	time-of-day 16	
85	$P_r + 850 \text{ ms}$	time-of-day 32	
86	$P_r + 860 \text{ ms}$	time-of-day 64	
87	$P_r + 870 \text{ ms}$	time-of-day 128	
88	$P_r + 880 \text{ ms}$	time-of-day 256	
89	$P_r + 890 \text{ ms}$	position identifier 9 (P_9)	
90	$P_r + 900 \text{ ms}$	time-of-day 512	
91	$P_r + 910 \text{ ms}$	time-of-day 1024	
92	$P_r + 920 \text{ ms}$	time-of-day 2048	
93	$P_r + 930 \text{ ms}$	time-of-day 4096	
94	$P_r + 940 \text{ ms}$	time-of-day 8192	
95	$P_r + 950 \text{ ms}$	time-of-day 16384	
96	$P_r + 960 \text{ ms}$	time-of-day 32768	
97	$P_r + 970 \text{ ms}$	time-of-day 65536	
98	$P_r + 980 \text{ ms}$	index bit (0)	
99	$P_r + 990 \text{ ms}$	position identifier 0 (P_0)	

Appendix B – PTP Standard Concepts (IEEE1588)

11.1 Description

The Precision Time Protocol (PTP) is an ultimate time synchronization accuracy protocol for Ethernet networks. On a local area network, it achieves clock accuracy in the sub-micro second range, making it suitable for applications where synchronization is essential to the measurement system. The ultimate time accuracy of the protocol is obtained from the compensation of propagation delay information between the source and destination.

IEEE 1588 - 2002 standard, officially entitled "Standard for a Precision Clock Synchronization Protocol for Networked and Control Systems", originally defined PTP protocol. In 2008, the standard was revised and had its protocol accuracy and robustness improved.

The protocol describes a hierarchical master-slave architecture designed for clock distribution, where the root timing reference is called Grandmaster clock, which transmits synchronization information to the clocks residing on its network segment.

11.2 Definitions according to IEEE 1588 Standard

- **Clock:** IEEE1588 standard defines a clock as a network device capable of using PTP protocol and providing a measurement of the passage of time since a defined epoch.
- **Synchronized Clocks:** According to IEEE1588 standard, two clocks are synchronized to a specified uncertainty if they have the same epoch and their measurements of time of a single event at an arbitrary time differ by no more than that uncertainty.
- **Master Clock:** According to IEEE1588, it is a clock that is the source of time to which all other clocks on that path synchronize.
- **Grandmaster Clock:** IEEE1588 defines a grandmaster clock, within a domain, as a clock that is the ultimate source of time for clock synchronization using the protocol.
- **Slave Clock:** IEEE1588 defines a slave clock as a clock that is coordinated with a master clock, i.e., it is capable of recognizing time Sync messages from a master clock.
- **Best Master Clock Algorithm:** According to IEEE1588, The Best Master Clock algorithm (BMC) performs a distributed selection of the best candidate clock to be used as clock source based on the following clock properties:
 - A universally unique numeric identifier for the clock. This is typically constructed based on a device's MAC address.
 - Time information quality is based on the time system adopted as reference.
 - Priority assigned to a clock in its configuration.

- Clock variance, which represents its stability based on observation of its performance over time.

The algorithm establishes an order of searching for the attributes and from the results, determines which will be used as time source.

- **Boundary Clock:** According to IEEE1588 standard, a boundary clock has multiple PTP ports in a domain and maintains the timescale used in the domain. It may serve as the source of time, i.e., be a master clock, and may synchronize to another clock, i.e., be a slave clock.
- **Ordinary Clock:** According to IEEE1588 standard, an ordinary clock has a single PTP port in a domain and maintains the timescale used in the domain. It may serve as a source of time, i.e., be a master clock, or may synchronize to another clock, i.e., be a slave clock.
- **Transparent Clock:** According to IEEE1588, a transparent clock is a device that measures the time taken from a PTP event message to transit the device and provides this information to clocks receiving this PTP event message.
- **One-step Clock:** According to IEEE1588 standard, it is a clock that provides time information using a single event message.
- **Two-step Clock:** According to IEEE1588 standard, it is a clock that provides time information using the combination of an event message and subsequent general message.
- **Accuracy:** According to IEEE1588 standard, the mean of the time or frequency error between the clock under test and a perfect reference clock, over an ensemble of measurements. Stability is a measure of how the mean varies with respect to variables such as time, temperature, and so on. The precision is a measure of the deviation of the error from the mean.
- **Profile:** According to IEEE1588 standard, profile is a set of all allowed PTP features applicable to a device.
- **Timeout:** According to IEEE1588 standard, timeout is the time in which a device waits to receive synchronization messages. In case the message is not received within this time interval, the clock that sends messages is considered out of operation and the BMC algorithm is run, and chooses a second master clock.

11.3 Multicast and Unicast Networks

The first revision of the IEEE1588 standard specifies only multicast network where a PTP message sent by a network port can be received by all other ports connected to the same network. The great advantage of the multicast network is that the master clock sends only one packet of time Sync to the network, and it is received by all slave devices connected to that network.

The second revision of the standard also specifies the form of unicast communication where the clock master has to send time synchronization packets for each slave device connected to the network, which requires the master clock to have greater processing power and causes the network traffic to be more overloaded.

11.4 PTP Synchronization

Through use of the BMC algorithm, PTP elects a master source of time for an IEEE1588 domain and for each network segment in the domain. Clocks determine the offset between themselves and their master. For a given slave device, the offset $o(t)$ at a time t is defined by:

$$o(t) = s(t) - m(t)$$

where $s(t)$ represents the time measured at the clock at physical time t , and $m(t)$ represents the time measured at the master at physical time t . The master clock periodically broadcasts the current time as a message to the other clocks. Under IEEE1588-2008, broadcasts are up to 10 messages per second.

Each broadcast begins at time $T1$ which is a Sync multicast message sent by the master to all the clocks in the domain. A clock receiving this message takes note of the local time $T1'$ when this message is received. The master may subsequently send a multicast Follow Up with accurate timestamp. Not all masters have ability to present an accurate timestamp in the Sync message. It is only after the transmission is complete that they are able to retrieve an accurate timestamp for the Sync transmission from their network hardware. Masters with this limitations use the Follow Up message to convey $T1$. Masters with PTP capabilities built into their network hardware are able to present an accurate timestamp in the Sync message and do not need to send Follow Up messages.

In order to accurately synchronize to their master, clocks must individually determine the network transit time of the Sync messages. The transit time is determined indirectly by measuring round-trip time from each clock to its master. The clocks initiate an exchange with their master designed to measure the transit time d . The exchange begins with a clock sending a Delay Req message at time $T2$ to the master. The master receives and time stamps the Delay Req at time $T2'$ and responds with a Delay Resp message. The master includes the time stamp $T2'$ in the Delay Resp message. Through these exchanges, a clock learns $T1$, $T1'$, $T2$ and $T2'$.

If d is the transit time for the Sync message, and $\tilde{o}$ is the constant offset between master and slave clocks, then:

$$T1 - T1' = \tilde{o} + d$$

$$T2 - T2' = -\tilde{o} + d$$

Combining the above two equations, we find that:

$$\tilde{o} = \frac{(T1' - T1 - T2' + T2)}{2}$$

The clock now knows the offset $\tilde{o}$ during this transaction and can correct itself by this amount to bring it into agreement with their other master.

11.5 Network protocols

IEEE1588 standard defines the network layers where the PTP protocol will be applied. It is possible to use PTP protocol in a network layer with IEEE 802.3 Ethernet (layer 2) or UDP/IPv4 (layer 3) connection.

The layer 3 (UDP/IPv4) is used in more environments facilitating the compatibility of sending and receiving messages between the devices connected to the network. Once the PTP protocol has low traffic when compared to other protocols, the network traffic is not limiting factor of the use of layer 3.

To use the layer 2 it is necessary that the network has ETHERNET connections between all master and slave clocks, which are not common when the network is divided into subnets and there is not an interconnection between them. The advantage of using layer 2 is that the traffic through the network is smaller because the sent packets do not require including IP and UDP address.

11.6 Clock operation mode

PTP protocol requires the master clock sending Sync messages periodically to all slave clocks connected to the network. Furthermore, master clocks must register and communicate to the slave clocks the exact timestamp in which the data packets were sent. This information can be sent in a single packet or two packets separately.

In One-step operation mode, the Sync information is sent in the same data packet as the timestamp of the message. In Two-step operation mode, the Sync information is sent in a data packet and the timestamp information of the message is sent in another one. The accuracy of both modes is the same.

11.7 Delay measurement mechanism

According to IEEE1588 a slave clock is capable of measuring the delay of message propagation that represents the time that a message takes to cross the master-slave path. The measurement of this delay is necessary to perform a time correction of the time of receipt of the message in relation to the time it was sent. The delay measurement is performed by sending messages containing the timestamp of the time of receipt to the master clock which sends a reply with information of the delay.

The second review of IEEE1588 standard, in 2008, specifies two ways of compensating delay: End-to-end and Peer-to-peer:

- End-to-end: measurement of delay across the network between master and slave clocks.
- Peer-to-peer: measurement of delay only between master and slave clocks as neighbors.

The advantage of P2P is that the time accuracy is immune to change in the network topology, since the delay between each master-slave connection is calculated for each packet sent. However, the P2P solution is possible

only when all devices in the network are transparent, i.e., they can perform delay measurement between one point and another. In network applications where the network comprises devices without measurement of delay, it is necessary to use the E2E mode, which calculates the delay in a general way between the two ends of the network.

11.8 Master, Slave and Grandmaster clocks

In PTP protocol, master clocks send message packets with Sync information, slave clocks receive and process the Sync messages and grandmaster clocks are the source of synchronization for the entire network.

IEEE1588 standard specifies the Best Master Clock algorithm (BMC) which selects the best candidate to be elected the master of the network, used as time source. The selection is performed from the attributes and attributed priorities to the possible candidates. The algorithm establishes a search order, and from the results, it determines which one will be the clock used as time source.

11.9 PTP Messages

In PTP protocol, Sync messages followed by the timestamp messages are sent to the entire network in multicast mode, in which a PTP message sent by a network port can be received by all other ports connected to the same network. The advantage of multicast mode network is that the master clock sends only one packet containing time information to the network and this packet is received by all slave devices connected to this network.

Among the messages specified by IEEE1588 standard, the ones that stand out are related to synchronization, timestamp and propagation delay. The Announce messages are used to inform the devices connected to the network about the existence of a master clock available to send Sync messages. The Announce message includes a packet of values that indicates the time accuracy of the clock, enabling the BMC algorithm to decide which of the available clocks will be used as master. The speed the Announce messages are sent influences directly the frequency the slave will perform the BMC algorithm. Many announce messages can be transmitted at the same time through the network and the slave clock is responsible to process these messages. All devices connected to the network that are able to operate as master should periodically send Announce messages to the network, becoming candidates to be master of the network.

The clock connected to the network selected as master by the BMC algorithm, should send Sync messages, and in case it is a two-step clock, it should also send a Follow Up message, containing a timestamp. The sending interval of the messages is configurable and its standard value, specified by IEEE1588 standard, is one-message-per-second. This interval specifies the frequency the slave devices receive synchronization information, allowing to adjust its internal clocks to use the master clock as

time reference. In the interval between two Sync messages the slave devices operate free from external time reference and the time stability in this period is determined by its internal time base, that can be, for example a crystal oscillator. By choosing the frequency to send Sync messages through the master clock, it is important to consider the accuracy of the internal clocks of the slave devices that will be synchronized by it, and also the bandwidth, because the higher the frequency to send messages is, the higher the network traffic is.

The delay measurement of messages passing through devices is important to reach the accuracy required by IEEE1588 standard. Especially in E2E networks, the propagation delay measurement is crucial for the synchronization. In networks with E2E delay measurement, the frequency the slave devices should measure delay, which results in sending and receiving messages, should be according to the network stability regarding the variation of this information.

Appendix C – Serial Datagrams

RT430/434 can be configured to send datagrams through serial ports. The datagrams defined for the unit are ACEB, NEMEA GPZDA, and Meinberg.

11.10 ACEB Datagrams

ACEB datagram comprises 13 bytes, sent once per minute in the second second of the minute (i.e. 12:00:02, then 12:01:02). The datagram information is described below.

Table 38: ACEB Datagram Information

Byte	Description	Possible values
1	Delimiter	0xFF
2	Header	0x01
3	Status	0x00 (locked) or 0x01 (not locked)
4	Start of transmission	0x02
5	Day of week	BCD 01 (Monday) ... BCD 07 (Sunday)
6	Year	BCD 00 ... 99
7	Month	BCD 01 ... 12
8	Day of month	BCD 01 ... 31
9	Hour	BCD 00 ... 23
10	Minute	BCD 00 ... 59
11	Second	BCD 02
12	End of transmission	0x03
13	Synch byte	0x16

11.11 NEMEA GPZDA Datagram

NEMEA ACEB datagram comprises 32 characters, sent once per second. The datagram information is described below:

\$GPZDA,hhmmss.0,DD,MM,YYYY,,*CC<CR><LF>

Table 39: GPZDA Datagram Time Information

Parameters	Possible values	Description
hh	00 ... 23	hours
mm	00 ... 59	minutes
ss	00 ... 59	seconds
ddd	001 ... 366	Julian day
DD	01 ... 31	day of the month
MM	01 ... 12	month
YYYY	2000 ... 2099	year (4 digits)

Table 40: GPZDA Datagram Line Feed and Carriage Return Information

Characters	ASCII (decimal)	ASCII (hexadecimal)	Description
<LF>	10	0A	line feed
<CR>	13	0D	carriage return

Table 41: GPZDA Datagram Checksum Information

Parameters	Description	Comments
CC	checksum	two hexadecimal digits representing the result of exclusive OR of all characters between '\$' and '*' ('\$' and '*' are excluded)

11.12 Meinberg Datagram

Meinberg datagram comprises 32 characters, sent once per second. The datagram information is described below:

<STX>D:DD.MM.YY;T:w;U:hh.mm.ss;uv__<ETX>

Table 42: Meinberg Datagram Time Information

Parameters	Possible values	Description
hh	00 ... 23	hours
mm	00 ... 59	minutes
ss	00 ... 59	seconds
DD	01 ... 31	day of the month
MM	01 ... 12	month
YY	00 ... 99	year (2 digits)
w	1 ... 7	day of the week (1 = Monday)

Table 43: Meinberg Datagram Beginning and End Information

Characters	ASCII	ASCII	Description
<STX>	02	02	start-of-datagram
<ETX>	03	03	end-of-datagram
_	32	20	space

Table 44: Meinberg Datagram Locked State Information

Parameters	Description	Comments
u	status	'_' se "locked", '#' if not
v	status	'_' se "locked", '*' if not

Appendix D – Antenna Delay Compensation

The antenna cable affects the unit's performance in two different ways: signal attenuation and signal propagation delay.

11.13 Signal Attenuation

Signal attenuation is related to cable type and overall cable length. When using the active antenna supplied by GE Vernova, total attenuation should not exceed 30 dB.

Total attenuation can be computed by using:

$$A = A_u \times l$$

Where A_u is the attenuation per unit length for the given cable and l is the overall cable length.

The table below shows a few typical cable configurations and the associated total attenuation.

Table 45: Antenna cables attenuation @ 1500 MHz (±1 dB)

Cable length	Cable RG58	Cable RG8
15 m (50 ft)	7 dB	—
25 m (82 ft)	12 dB	—
40 m (131 ft)	19 dB	—
75 m (246 ft)	—	13 dB
100 m (328 ft)	—	18 dB
125 m (410 ft)	—	22 dB
150 m (492 ft)	—	26 dB

11.14 Propagation Delay

The antenna cable delays the signal received from the satellites. In applications in which the ultimate time accuracy is desired, this delay should be compensated inside the unit.

Typically, the delay introduced by coaxial cables is in the magnitude of 4 ns/m (1.2 ns/ft) of cable length.

The exact delay can be computed by using:

$$T = \frac{1}{CK_v} \times l$$

Where $C = 3 \times 10^8$ m/s is the speed of light, $K_v = 0.8 \dots 0.85$ is a constant which depends on the cable and l is the cable length in meters. The table below summarizes some typical delays caused by coaxial cables.

Table 46: Attenuation of typical antenna cables

Cable length	Typical delay
15 m (50 ft)	60 ns
20 m (82 ft)	100 ns
50 m (164 ft)	200 ns
75 m (246 ft)	300 ns
100 m (328 ft)	400 ns
125 m (410 ft)	500 ns
150 m (492 ft)	600 ns

Appendix E – Application Examples

11.15 Application Example 1: Traditional and Modern Time Sync

The first example illustrates the traditional and modern manners to synchronize devices, using a single time source: RT430. In the left, the clock provides NTP and IRIG-B for legacy IEDs, and in the right, the PTP represents the modern protocol for time synchronization. Using Ethernet networks, the PTP is distributed through PTP-aware Ethernet switches and whenever a legacy IED needs to be included in a modern architecture, the RT431 acts as a PTP translator converting PTP to IRIG-B or PPS.

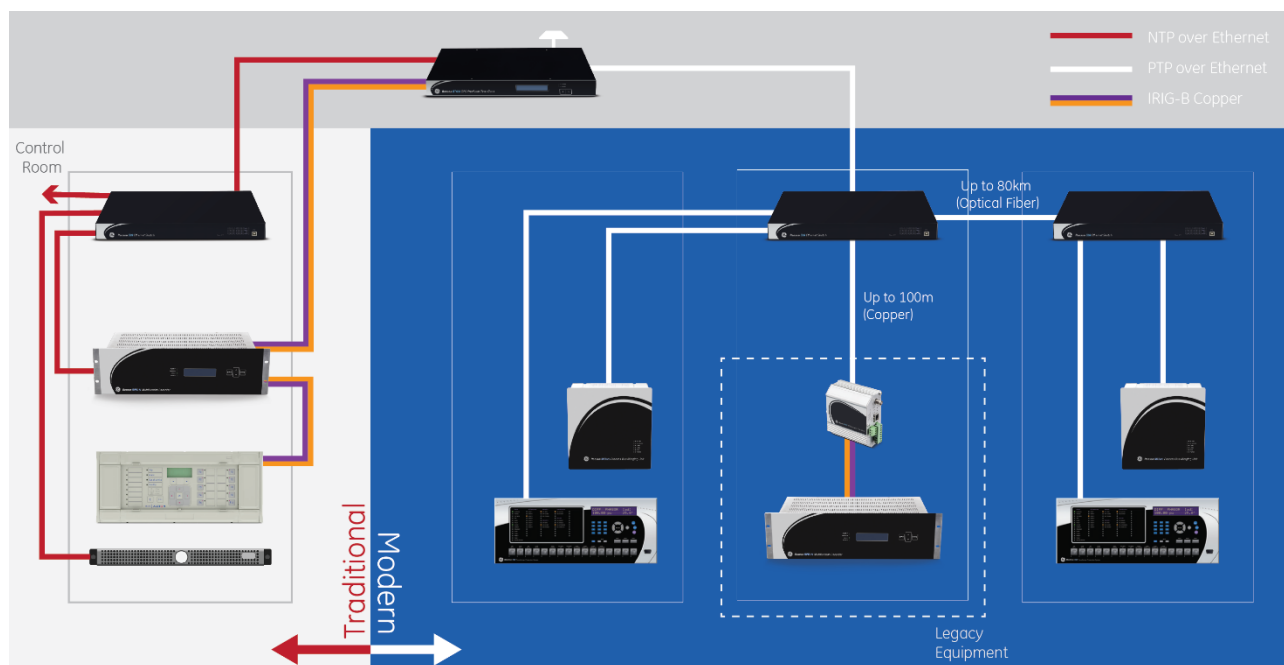


Figure 45: Traditional x Modern Time Synchronization

11.16 Application Example 2: System Wide Grandmaster Clock

Using the RT430 along with GE JunglePAX is a great way to have PTP over a wide network. The next figure exemplifies an architecture which a given application has a local PTP Grandmaster clock, which commonly will be the Best Grandmaster Clock for the local IEDs. Whenever this local clock became unavailable or does not represent the best accurate clock, the local IEDs can count with a remote PTP Grandmaster clock, which is called as System Wide Grandmaster.

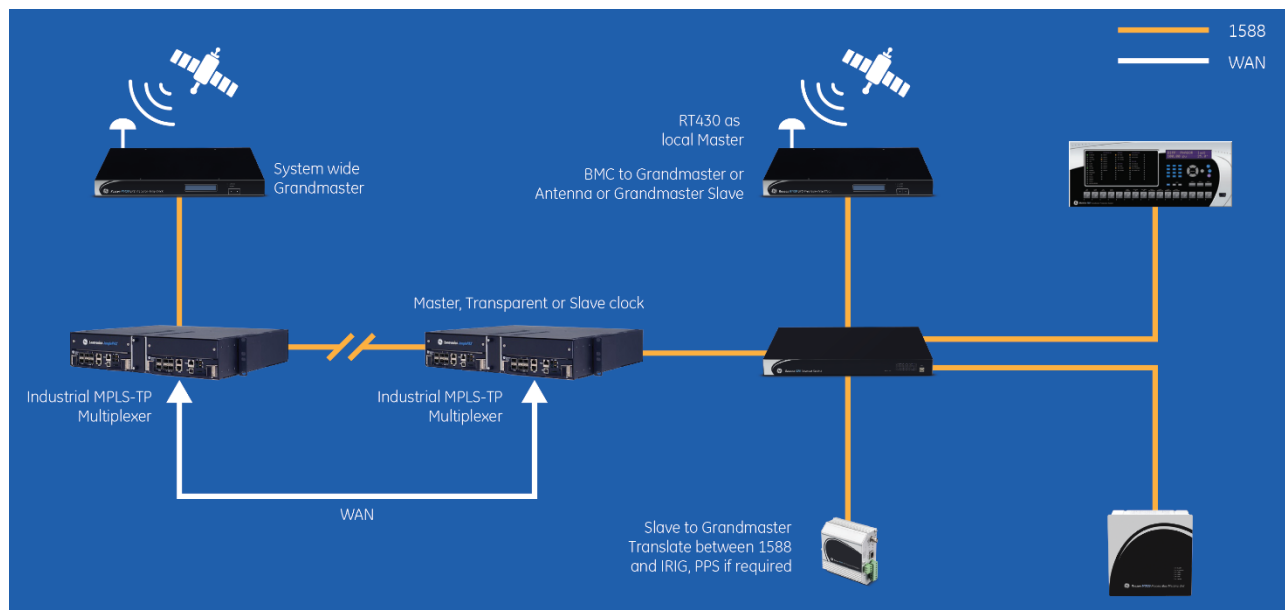


Figure 46: System Wide Grandmaster Clock

11.17 Application Example 3: Synchrophasor, TWFL and Process Bus Applications

Requiring 1 μ s time accuracy, this third example demonstrate the best way to synchronize devices used for Synchrophasor (PMU), Travelling Waves Fault Locators (TWFL) and Process Bus devices.

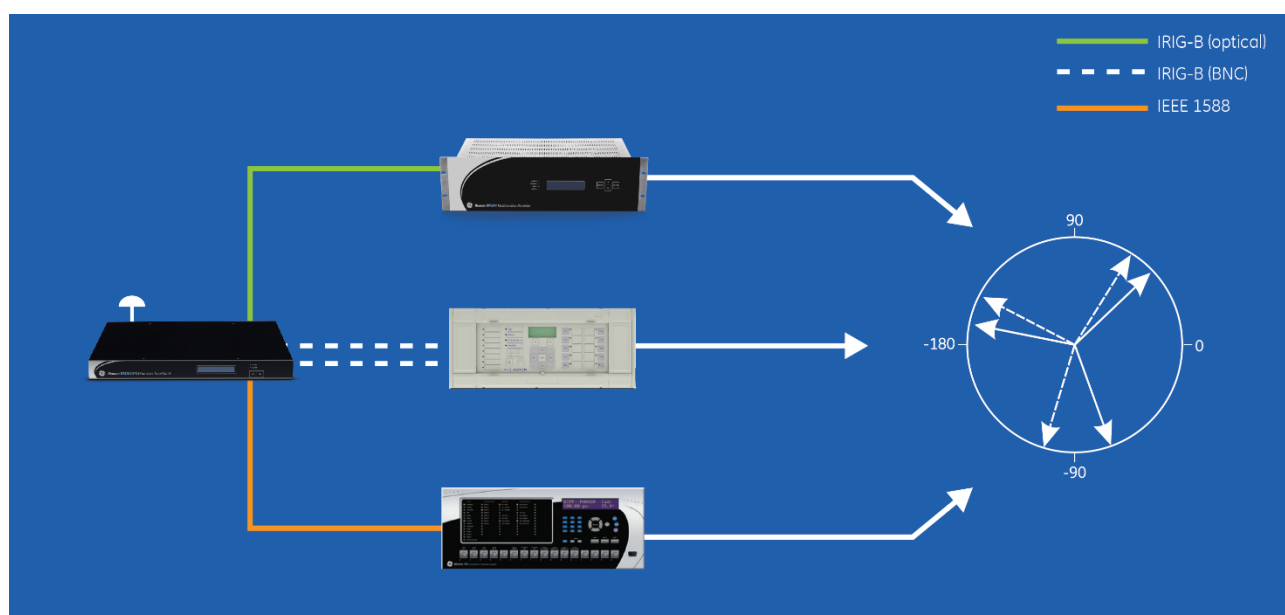


Figure 47: Synchrophasor devices synced by RT430/434

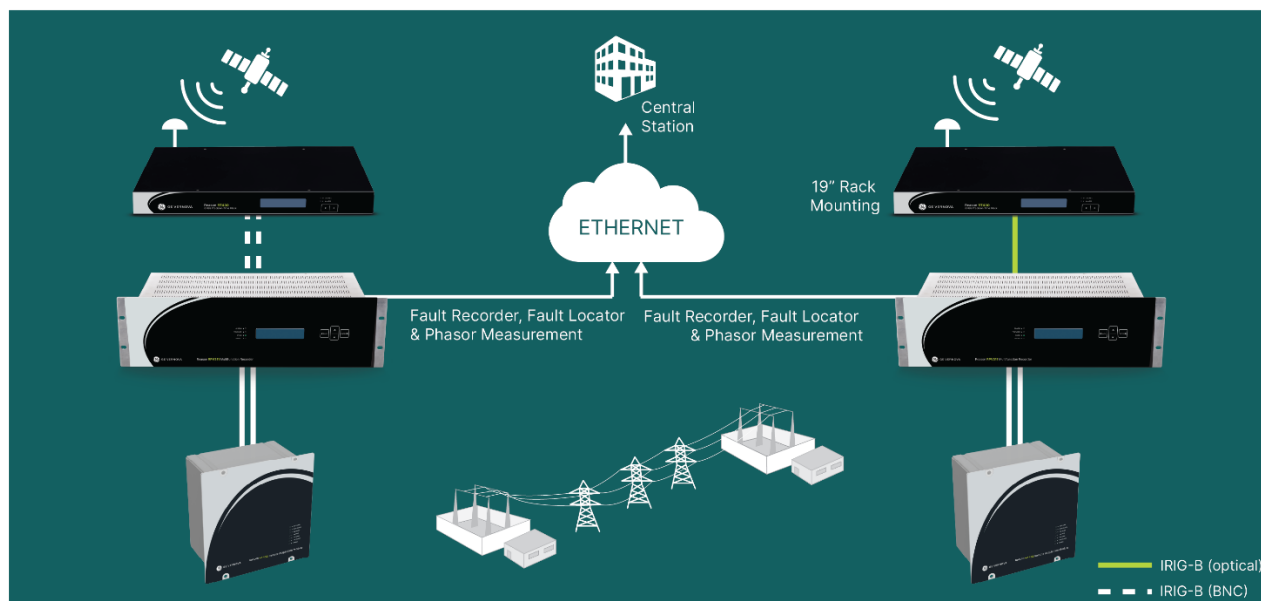


Figure 48: TWFL application using RT430/434 for Time Sync

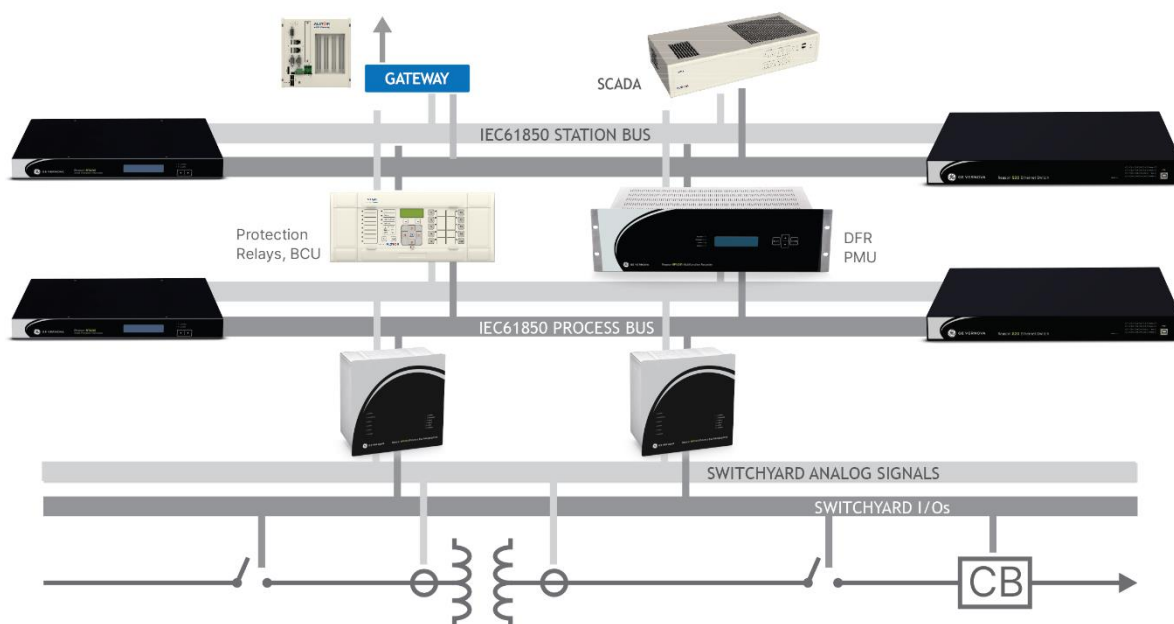


Figure 49: Process Bus application using PTP via the Station Bus network.

11.18 Application Example 4: IEEE 1588 in a PRP Network

RT430 offers the highly accurate IEEE 1588v2 Precision Time Protocol (PTP) combined with the Parallel Redundancy Protocol IEC 62439-3:2016, ensuring 100 ns accuracy and high availability in time synchronization over Ethernet networks. In case of failure in one of the redundant networks, the recovery-time for the PTP is zero. In other words, the PRP architecture

overcomes any single network failure without affecting the data transmission.

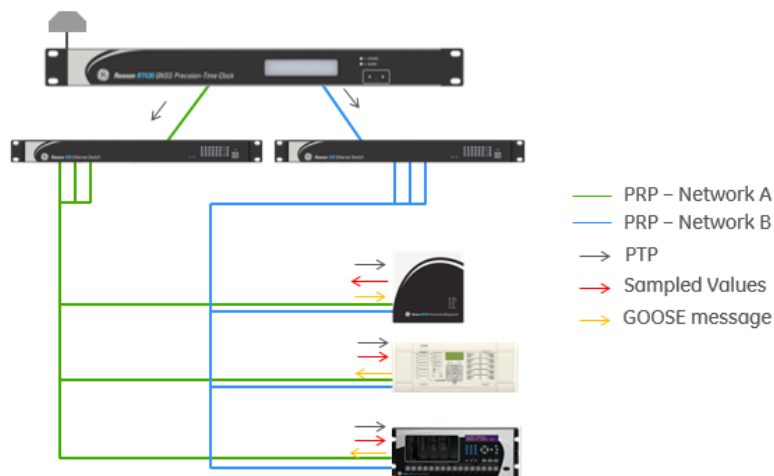


Figure 50: PTP in a PRP network.

11.19 Application Example 5: Time Sync Expansion using RT411 and RT412

In applications where a higher number of TTL or ST outputs are required for IRIG-B/PPS, the RT411 is a cheap solution to expand the number of outputs from clocks. Furthermore, the RT412 can convert optical signals to electrical and vice versa, which is a great solution to distribute time synchronization. The next figure demonstrates an IRIG-B time distribution using only one clock plus a RT411 and many RT412, used in Automation & Control architectures.

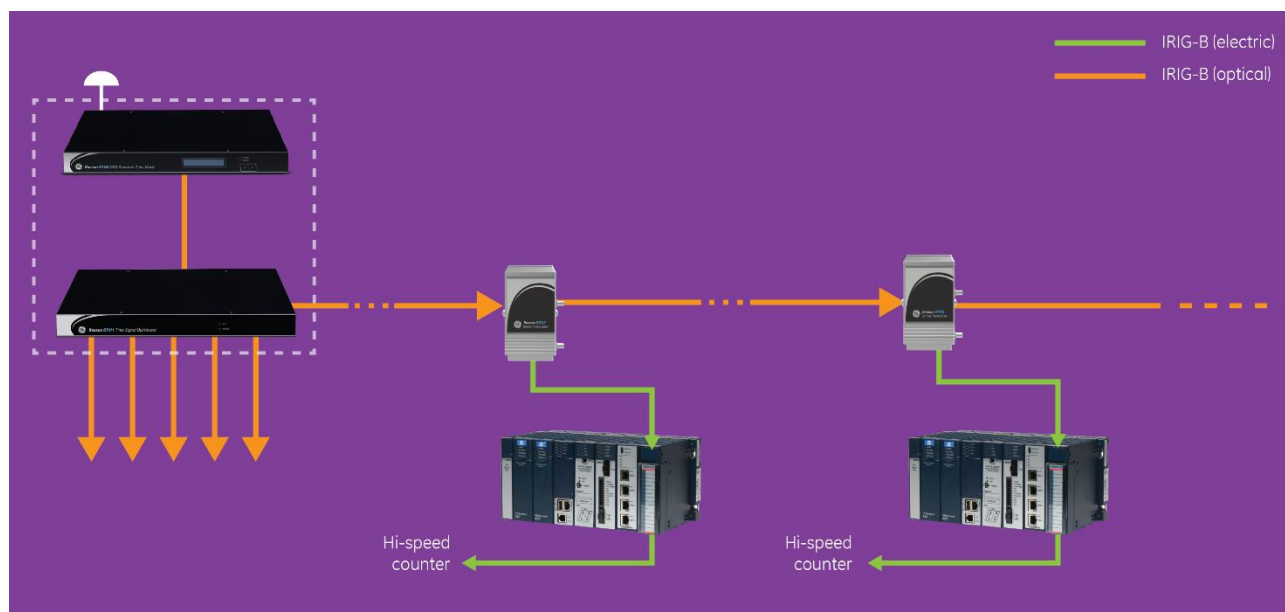


Figure 51: Time Sync expansion using RT411 and RT412

Appendix F – Kit Mounting for GNSS Antenna (Q065)

A kit mounting for walls (ordering code Q065) is available to install the GNSS antenna (code Q020) supplied by GE.

The kit mounting dimensions and composition are as follows.

Table 47: Dimensions specification of antenna kit mounting

Height	Body: 150 mm (5.9 in) Pipe: 500 mm (19.7 in)
Width (body)	181.7 mm (7.2 in)
Depth (body)	217.7 mm (8.6 in)

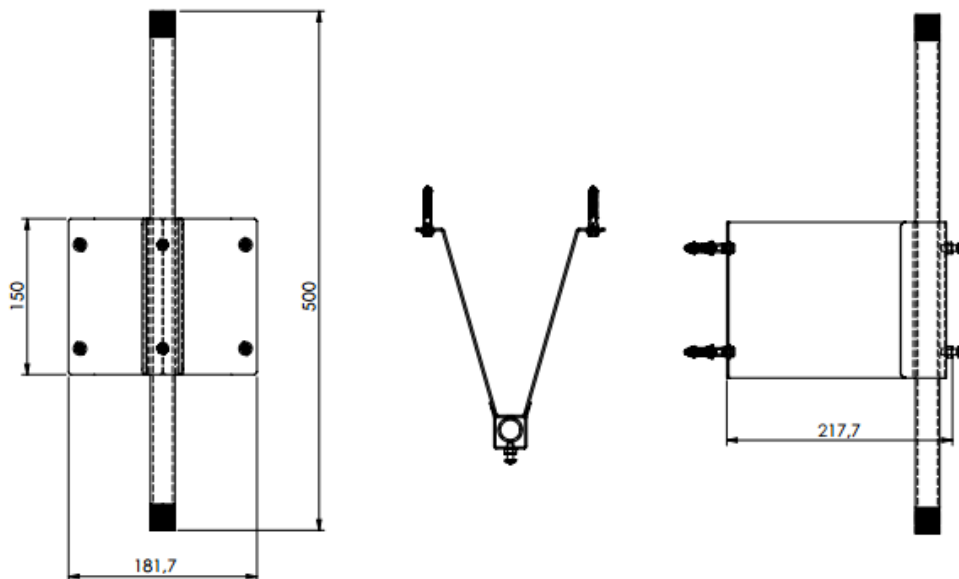


Figure 52: Dimensions of antenna kit mounting

Table 48: Description of items from kit mounting

Number 1	Main structure of kit mounting (Stainless steel)
Number 2	Phillip screws M6x16 (Stainless steel)
Number 3	S8 nylon plugs
Number 4	Self-tapping screw 3/16"x45 (Stainless steel)
Number 5	M6 Washer (Stainless steel)
Number 6	3/4" PVC pipe with 1.814 mm thread in both ends

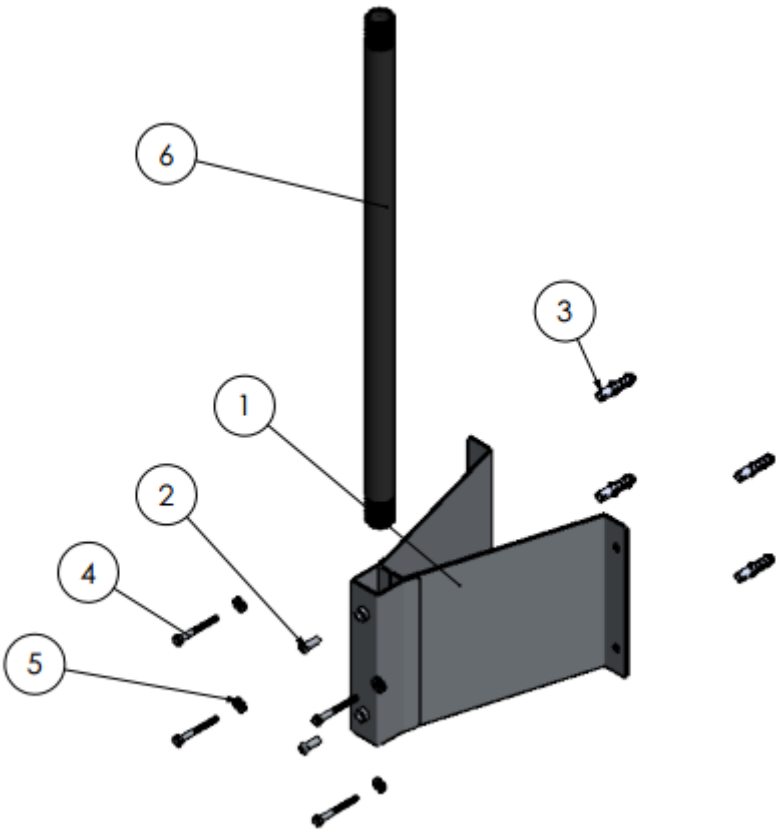


Figure 53: Items from antenna kit mounting