

Wind Farm Service Vessel - SeaStream* DP Special Functions

GE, a global leader in the delivery of wind farm projects and infrastructure, has first-hand experience of the wind farm power generation and maintenance business. GE's latest generation of SeaStream* Dynamic Positioning (DP) brings that experience to life to maximise efficiency and operational effectiveness within the challenging environment of the offshore wind farm.

GE's SeaStream* DP functions for wind farm service vessels enables:

- Efficient and rapid movement between individual wind turbines
- Effective planning of moves/transitions from turbine to turbine
- Clear and unambiguous information exchange between marine crew and planning crew
- Planning station integrated into the DP display (option for standalone planning station)
- Early gangway deployment
- Rapid establishment of stable DP control at each new destination. Minimum time taken to become fully operational with gangway deployed
- **Effective Dynamic Position control** throughout the process of gangway deployment, use and recovery.

Efficient and reliable

Overall operational efficiency is supported by reducing the time taken to move between individual wind turbines and to establish full stable DP control at the new location:

PLANNING

- The location of each wind turbine is pre-entered in the DP system software on the planning page. The DP operator can select/de-select a view of the entire wind farm turbine array on the DP screen for planning and operations.
- If preferred a separate, stand -alone, planning station can be provided.
- The DP operator interacts with the touch screen to select individual waypoints and their sequence. The selected waypoint sequence defines the route (vessel track) for the transit move.

POSITION MOVES - FAST AND EFFICIENT

 Transit waypoints are permanently held (in their inactive state unless selected by the DP operator) and displayed at a diagonal mid-point between each 'set' of 4 wind turbines.



- The vessel is moved through an operator selected series of transit waypoints.
- On arrival at the selected transit waypoint point the vessel is smoothly moved to the destination waypoint alongside the chosen wind turbine
- Progression through transit waypoints and to the
 destination waypoint uses the DP functionality to
 accelerate the vessel along the track within a range of
 pre-set speeds. Where possible the DP tracking process
 employs all available thrusters such that the vessel
 progress is controlled as a fully 3 axis move (equivalent to
 Auto Track). Where vessel speed exceeds a predetermined
 speed at which bow tunnel thrusters become ineffective
 the DP system controls vessel progress along the track
 using main propulsion thrusters (equivalent to Auto Sail).
- At a predetermined distance from the new location the vessel speed is ramped down and the bow thrusters are again used to establish full 3 axis control prior to arrival at the waypoint.
- Transitions between control philosophies are, wherever reasonable, managed automatically without additional operator intervention.

EFFECTIVE DP - GANGWAY CONNECTED

- At a pre-selected distance from the selected destination waypoint the DP system initiates a command to the gangway operator signalling that early deployment of the gangway can begin.
- On arrival at the new location the GE's Fast Learn function is activated to assist with the rapid settling into a stationary DP state (position and heading). Fast Learn significantly reduces time taken to establish stable DP control.
- The gangway movements (elevation, azimuth and extension) are monitored and input to the DP controller for position keeping.

Gangway Interface

Analogue Interface (4-20 mA):

- Gangway azimuth (horizontal plane)
- · Gangway Elevation (vertical plane)
- Gangway Extension
- Gangway force

Digital Interface:

Gangway connected

Position Measuring Equipment

Position measuring systems choices significantly impact vessel operational effectiveness and efficiency as well as system capital costs.

Examples of position measuring systems that can be considered are:

- GNSS/DGNSS
- Laser (multiple target, single target and zero target variants)
- Radar (target versions and zero target variants)
- Doppler velocity log

Wind Farm Service Vessel SeaStream Dynamic Positioning Special Features

GENERAL

- Latest SeaStream* model
- Mariner friendly for efficient operations

PLANNING FUNCTIONS

- Wind farm set up manually or via serial data
- Operator view of the entire wind farm
- Predetermined waypoints
- Operator selection of waypoint transit sequence
- Integrated planning station (option for standalone planning station)

POSITION MOVES

- Smooth transition between waypoints
- Ramped acceleration and slow down

GANGWAY CONNECTED

- Gangway interfaced to DP (elevation, azimuth, extension and force)
- Fast Learn function for rapid establishment of stable DP control



To find out more about GE's Wind Farm Service Vessel - SeaStream* DP Special Functions, please contact:

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